ON ANGULAR MEASURE IN A METRIC SPACE

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(Received July 15, 1955)

H. Busemann [1] dealt with a metric space called a G-space. If a G-space $\mathfrak S$ is of dimension 2, then we can generally define an angular measure Ψ [§ 1]. In this note, we define a function F on figures of $\mathfrak S$ which will be called the excess function [§ 2]. When the angular measure Ψ is continuous and the function F is of bounded variation, we define the Gaussian curvature in the general sense which will be called the generalized Gaussian curvature of $\mathfrak S$ [§ 2]. If $\mathfrak S$ is a G-space with constant curvature in H. Busemann's sense, then the angular measure Φ is introduced [5], [§ 3]. If the excess function F defined by means of the angular measure Φ is of bounded variation, then $\mathfrak S$ is a G-space with constant generalized Riemannian curvature [§ 4]. The main purpose of this note is to show that Gauss-Bonnet's theorem holds in $\mathfrak S$ and all G-spaces with constant curvature are divided into three classes according as its generalized Riemannian curvature is positive, zero, or negative.

- 1. In a metric space points will be denoted by small roman letters and the distance between two points x and y by xy. According to H. Busemann $[1; \S 4]$ the axioms for a space \S to be a G-space are the following:
 - A. S is metric with distance xy.
 - B. S is finitely compact.
 - C. S is convex metric.
- D. Every point x of (b) has a neighborhood $S(x, \alpha(x))$ ($= \{y \mid xy < \alpha(x)\}$) ($\alpha(x) > 0$) such that for any positive number ε and any two points a and b in $S(x, \alpha(x))$ there exist positive numbers $\delta_t (\le \varepsilon)$ (i = 1, 2) for which a point a_1 with $a_1a + ab = a_1b$ and $a_1a = \delta_1$ and another point b_1 with $ab + bb_1 = ab_1$ and $bb_1 = \delta_2$ exist and are unique.

For any two points x and y, the axioms A, B, and C guarantee the existence of a segment T(x,y) from x to y (or T(y,x) from y to x) whose length is equal to the distance xy. The prolongation of a segment is locally possible and unique under the axiom D. The whole prolongation of a segment is said to be an extremal. An extremal x has a parametric representation $x(\tau)$, $-\infty < \tau < +\infty$, such that for every x_0 a positive number $x(\tau)$ exists such that $x(\tau_1)x(\tau_2) = |\tau_2 - \tau_1|$ for $|\tau_1 - \tau_0| \le x(\tau_0)$ ($x(\tau)$). The extremal x is said to be a straight line, if its parametric representations have the property: $x(\tau_1)x(\tau_2) = |\tau_2 - \tau_1|$ for any two real numbers $x(\tau)$ and $x(\tau)$. If every extremal is a straight line, then $x(\tau)$ is said to be a straight line space.

In [1; § 4] the number $\eta_{\lambda}(x)$ ($\lambda \ge 2$) and the term "direction" were introduced. $\eta_{\lambda}(x)$ is defined as the 1. u. b. of those β for which every segment

with end points in $S(x, \beta)$ is a cocentral subsegment of a segment of length $\lambda \beta$. $\eta_{\lambda}(x)$ is positive for every point x and every number λ not less than 2. The number $\eta(x)$ is defined as $\min(\eta_0(x), 1)$. Then $\eta(x)$ is regarded as a continuous function of a point x. The segment T(a, b) of length $\eta(a)$ is said to be a direction with the initial point a.

2. Let $\mathfrak S$ be a G-space of dimension 2 and p any point of $\mathfrak S$. Let $\mathfrak x_1$ and \mathfrak{x}_2 be two different half extremals issuing from p whose parametric representations are given by $x_1(\tau)$, $0 \le \tau < +\infty$, and $x_2(\tau)$, $0 \le \tau < +\infty$, respectively. Then $S(p, \eta(p))$ is divided by the directions $x_1(\tau)$, $0 \le \tau \le \eta(p)$, and $x_2(\tau)$, $0 \le \tau \le \eta(p)$ $\tau \leq \eta(p)$, into two sectors D_1 and D_2 . Similarly $S(p, 2\eta(p))$ is divided by $x_1(\tau)$, $0 \le \tau \le 2\eta(p)$, and $x_2(\tau)$, $0 \le \tau \le 2\eta(p)$, into two sectors D_1 and D_2 . We assume $D_i \subset D'_i (i = 1, 2)$. Then only one of D'_i and D'_i contains all segments T(x, y)with $x \in E[x_1(\tau), 0 \le \tau \le \eta(p)]^{1}$ and $y \in E[x_2(\tau), 0 \le \tau \le \eta(p)]$, unless y_1 and y_2 are opposite. Let D_1 be such a sector. Then D_1 is called a convex sector and D_2 a concave sector. The segments $x_i(\tau)$, $0 \le \tau \le \eta(p)$, are called the legs of $D_i(i=1,2)$. $S(p,\eta(p))$ is said to be the normal neighborhood of p.

At a point p an angular measure Ψ_p is defined as a function on the set of all sectors of $\overline{S(p,\eta(p))}$ which fulfills the following conditions 1°, 2°, and 3° .

- 1. $\Psi_p(D) \ge 0$ for any sector D.
- 2. $\Psi_p(D) = \pi$, if and only if the two legs of D are opposite.
- 3. If two sectors D_1 and D_2 have only one common leg but have no common part, then $\Psi_p(D_1) + \Psi_p(D_2) = \Psi_p(D_1 + D_2)$.

In such a way angular measure Ψ_p is defined at every point p of \mathfrak{S} . Then we denote by Ψ the function Ψ_p . The function Ψ is said to be an angular measure on \mathfrak{S} . It is easy to see that $\Psi(D) = 0$, if and only if D is a segment.

Let p be a point of \mathfrak{S} and $\{p_{\nu}\}$ any sequence of points which converges to p. Let D_{ν} be any sector of each $S(p_{\nu}, \eta(p_{\nu}))$ such that $\mathrm{Fl}_{\nu \to +\infty}$ $D_{\nu} = D^{2}$. If $\lim_{\nu \to +\infty} \Psi(D_{\nu}) = \Psi(D)$, then the angular measure Ψ is said continuous at p.

A triangle abc is said to be normal, if the vertices a, b, and c are not collinear and the normal neighborhood of each of these vertices contains the others. Let D be the convex sector of $\overline{S(a, \eta(a))}$ whose legs contain the segments T(a, b) and T(a, c). Then $\Psi(D)$ is called the inside angle of the triangle abc at a and denoted by bac (or cab). Similarly abc and acb are defined. From the definition of normal triangles we see that each inside angle is less than π . It is also easily seen that the angle between two segments T(p, a) and T(p, b) is defined. We denote it by apb.

To define the excess function F, we put

$$F(\sigma) = bac + cba + acb - \pi$$

 $F(\sigma)=\stackrel{\smallfrown}{bac}+\stackrel{\smallfrown}{cba}+\stackrel{\smallfrown}{acb}-\pi$ for a normal triangle $\sigma(=abc)$. Then F is a function on the set of all

¹⁾ $E[x_1(\tau), 0 \le \tau \le \eta(p)]$ means the set of all points of the segment $x_1(\tau), 0 \le \tau \le \eta(p)$.

We use the same notation for half extremals and extremals.

F1 means the closed limit introduced by Hausdorff [1], [4]

normal triangles on \mathfrak{S} . It is easy to see $F(\sigma) < 2\pi$ for every normal triangle on \mathfrak{S} . We assume that F vanishes for empty set. The following property of the function F is clear from the definition.

(2.1) If two normal triangles σ_1 and σ_2 are non-overlapping, namely $\sigma_1^{\circ}\sigma_2 = \sigma_1\sigma_2^{\circ} = \phi^{3}$ and $\sigma_1 + \sigma_2$ is also a normal triangle σ_3 , then

$$F(\sigma_1) + F(\sigma_2) = F(\sigma_3).$$

A set which is expressible as the sum of a finite number of non-overlapping normal triangles is called a figure.

(2.2) If a figure R is expressed as the sum of a finite number of normal triangles in two ways $\sum_{i=1}^{m} \sigma_i$ and $\sum_{i=1}^{n} \sigma'_i$, then the relation

$$\sum_{i=1}^m F(\sigma_i) = \sum_{i=1}^n F(\sigma_i')$$

holds and this common value is given by

$$F(R) = 2\pi \chi(R) - \pi \chi(R') - \Sigma(\pi - v_i),$$

where R' is the boundary of R, $\mathcal{X}(R)$ and $\mathcal{X}(R')$ the Euler characteristics of R and R' respectively and v_i the angle at each vertex a_i measured in R.

(2.2) easily follows from a result obtained by S. Cohn-Vossen [2] for a 2-dimensional Riemannian surface.

From the above the function F is regarded as a function on the set of all figures on \mathfrak{S} . F is said to be the excess function on \mathfrak{S} . In a 2-dimensional Riemannian space F(R) is the total curvature of a figure R.

On a figure R the upper and lower variations of the function F are denoted by $\overline{W}(F;R)$ and W(F;R) respectively. The total variation $\overline{W}(F;R)$ + $|\underline{W}(F;R)|$ is denoted by W(F;R). If $W(F;R) < +\infty$ for any figure R on \mathfrak{S} , then the function F is of bounded variation on \mathfrak{S} and we have by Jordan's Decomposition Theorem

- (2.3) $F(R) = \overline{W}(F; R) + \underline{W}(F; R)$ for every figure R.
- If $\mathfrak S$ is a 2-dimensional Riemannian space, then by Gauss-Bonnet's Theorem F is absolutely continuous.
- (2.4) THEOREM. If the angular measure Ψ is continuous and the excess function F is of bounded variation on \mathfrak{S} , then F is continuous at every point.

PROOF. At first we prove that the absolute variation W(F; R) is continuous.

Suppose that W(F; R) is not continuous at a point p. Then a positive number \mathcal{E} and a sequence of normal triangles $\{\sigma_{\nu}\}$ which tends to p exist such that

$$W(F; \sigma_{\nu}) > \varepsilon$$
 for each ν .

We shall show that it is possible to define a sequence of non-overlapping figures $\{R_{\nu}\}$ such that

³⁾ The interior of a set X is denoted by X° .

(2.5)
$$p \in R_{\nu}$$
 and $|F(R_{\nu})| > \varepsilon/2$ for each ν .

The normal triangle σ_1 clealy contains a figure R_1 such that $|F(R_1)| > \varepsilon/2$. If $R_1 \ni p$, the figure R_1 satisfies the condition (2.5). If $R_1 \ni p$, then by choosing a suitable triangle σ_1' we have a figure $R_1 \ominus \sigma_1' \ (= (\overline{R_1 - \sigma_1'})^\circ)$ such that $R_1 \ominus \sigma_1' \ni p$ and $|F(R_1 \ominus \sigma_1')| > \varepsilon/2$ since the angular measure Ψ is continuous. The figure $R_1 \ (= (R_1 \ominus \sigma_1'))$ satisfies the condition (2.5).

Suppose that the figures R_1, R_2, \ldots , and R_{ν} have already been chosen and let σ_{λ} be the first normal triangle of $\{\sigma_{\nu}\}$ which does not overlap any of the figures R_1, R_2, \ldots and R_{ν} . In the same way as in the above we can see that σ_{λ} contains a figure $R_{\nu+1}$ which fulfills (2.5). Thus we have a sequence of figures as described in the above.

Let R be a figure such that $R \supset R_{\nu}$ for each ν . Then we have

$$W(F; R) \geq \sum_{\nu=1}^{n} W(F; R_{\nu}) > \sum_{\nu=1}^{n} |F(R_{\nu})| > n\varepsilon/2.$$

But this contradicts to the fact that the function F is of bounded variation. From this it follows that the upper and lower variations are continuous. Hence, by virtue of Jordan's Decomposition Theorem, (2.4) is proved.

When the function F is of bounded variation, we denote by F^* the additive function of a set induced by F. Then the following (2.6) is obvious (See [3; Chap. III, § 6]).

(2.6) Under the assumption of (2.4) $F^*(R) = F^*(R^\circ) = F(R)$ for every figure R on \mathfrak{S} .

For any subset X of $\mathfrak S$ the 2-dimensional Hausdorff measure $\mu(X)$ is defined. We assume that the 2-dimensional Hausdorff measure of every bounded set is finite. Then we have by Lebesgue Decomposition Theorem and Radon-Nykodym's Theorem

$$F^*(X) = T^*(X) + \int_{\mathbb{R}} \frac{1}{k} d\mu(x)$$

where X is a Borel set, T^* the function of singularities of F^* , and 1/k an integrable function uniquely determined at almost all points on \mathfrak{S} . Putting: $T^*(R) = T(R)$, we have by (2.6)

$$F(R) = T(R) + \int \frac{1}{k} d\mu(x).$$

The function 1/k will be said the generalized Gaussian curvature of \mathfrak{S} . If the function F is monotone, then F is non-decreasing or non-increasing according as F is non-negative or non-positive. Hence we have

$$\int_{a}^{1} \frac{1}{k} d\mu(x) \leq b \stackrel{\wedge}{ac} + c \stackrel{\wedge}{b} a + a \stackrel{\wedge}{c} b - \pi \quad \text{or}$$

⁴⁾ Let X be any subset of S and, for a given ε , Λ the class of all countable coverings Σ $(X_i = X)$ with diam $X_i < \varepsilon$. Then the 2-dimensional Hausdorff measure $\mu(X)$ is defined as $(\pi/4) \lim \{\inf_{\Lambda} \Sigma (\operatorname{diam} X_i)^2\}$.

$$\int_{a}^{\infty} \frac{1}{k} d\mu(x) \ge b \hat{a} c + c \hat{b} a + a \hat{c} b - \pi$$

for every normal triangle σ (= abc) according as F is non-negative or non-positive.

3. In this paragraph we study a G-space with constant curvature in H. Busemann's sense. If in a G-space every point p has a spherical neighborhood $S(p, \rho(p))$ such that the bisector $B(a, a')^{(5)}$ of any two distinct points a and a' in $S(p, \rho(p))$ is linear in this neighborhood, then the space is said to be with constant curvature.

In such a space \mathfrak{G} , for every point p there exists a positive number $\delta(p)$ $(5\delta(p) = \overline{\delta}(p) < \min(\rho(p), \eta(p))$ which satisfies the following conditions [1; § 15].

- (1) The neighborhood $S(p, \delta(p))$ is homeomorphic to the interior of a finite dimensional euclidean sphere; (2) if the dimension of \mathfrak{G} is $n \ (\geq 2)$, $S(p, \bar{\delta}(p)) \cap B(a, a')$ $(a, a' \in S(p, \bar{\delta}(p)))$ is of dimension (n-1) (we put $B_p(a, a') = B(a, a') \cap S(p, \bar{\delta}(p))$) and call this a hyperplane); (3) Every sphere is strictly convex for $0 < \alpha \leq \bar{\delta}(p)$; (4) every point x of $S(p, \bar{\delta}(p))$ has a unique foot f on a hyperplane B_p which intersects $S(p, \bar{\delta}(p))$; (5) a mapping $\Omega(B_p)$ of $S(p, \bar{\delta}(p))$, which is a motion, is defined as follows:
 - (a) $x\Omega(B_p) = x$ for every point $x \in B_p$, and
- (b) if $x \in S(p, \delta(p)) B_p$, the point $x' = x\Omega(B_p)$ is determined by xf = fx' = xx'/2.

The mapping $\Omega(B_p)$ is said to be the reflection of $S(p, \delta(p))$ with respect to B_p . All G-spaces with constant curvature are divided into two classes as follows [5]:

- I. The class of G-spaces of Type I. If a G-space \mathfrak{G} is of Type I, then the universal covering space \mathfrak{G} of \mathfrak{G} has the following properties:
- (1) Every extremal is closed; (2) every extremal through a point p passes through a unique point p' called the conjugate point of p; every extremal subarc from p to p' is a segment of constant length κ ; (4) every sphere with radius less than $\kappa/2$ is strictly convex; (5) the bisector of any two distinct points is linear and coincides with a sphere of radius $\kappa/2$.
- II. The class of G-spaces of Type II. If a G-space ${}^{\textcircled{G}}$ is of Type II, then the universal covering space ${}^{\textcircled{G}}$ of ${}^{\textcircled{G}}$ has the following properties:
- (1) $\widetilde{\mathfrak{G}}$ is a straight line space; (2) every sphere is strictly convex; (3) the bisector of any two distinct points is linear and of dimension (n-1).

On account of $(5)_{I}$ and $(3)_{II}$, the bisector of two distinct points is said to be a subspace of dimension (n-1).

Let $\mathfrak S$ be a G-space with constant curvature and of dimension 2. The angular measure Φ is introduced as follows:

⁵⁾ The bisector of two distinct points a and a' is defined as the set $\{x \mid ax = a'x\}$.

⁶⁾ A set E is said linear, if for any two points x and x' of E there exists a segment T(x, x') contained in E.

Let p be any point of \mathfrak{S} and a line⁷ \mathfrak{g}_p through p intersect the circle $K(p, \delta(p)/2)$ at points a and a'. The line $B_p(a, a')$ is perpendicular⁸ to T(a, a') at p. Let $B_p(a, a')$ intersect $K(p, \delta(p)/2)$ at points b and b'. Then the segments T(a, a') and $T(b \ b')$ divide $\overline{S(p, \delta(p)/2)}$ into four convex sectors \widehat{apb} , $\widehat{bpa'}$, $\widehat{a'pb'}$, and $\widehat{b'pa}$. For these sectors we put

$$\Phi_{p}(\widehat{apb}) = \Phi_{p}(\widehat{bpa'}) = \Phi_{p}(\widehat{a'pb'}) = \Phi_{p}(\widehat{b'pa}) = \pi/4.$$

Let $B_{p}(a,b)$ intersect $K(p,\delta(p)/2)$ at points c and c' and $B_{p}(a',b)$ $K(p,\delta(p)/2)$ at points d and d'. Then each of the above four sectors is divided by either $B_{p}(a,b)$ or $B_{p}(a',b)$ into two convex sectors. We denote these sectors by \widehat{apc} , \widehat{cpb} , $\widehat{bpd'}$, $\widehat{a'pa'}$, $\widehat{a'pa'}$, $\widehat{a'pc'}$, $\widehat{c'pb'}$, $\widehat{b'pd}$ and \widehat{dpa} and put

$$\Phi_{p}(\widehat{apc}) = \ldots = \Phi_{p}(\widehat{dpa}) = \pi/8.$$

We continue this process. If we denote by A the set of points $\{a, a'; b, b'; c, c'; \ldots \}$, then the closure A coincides with the circle $K(p, \delta(p)/2)$. For any sector \widehat{apq} , by taking a sequence of points $\{q_v\}$ $(q_v \in A)$ which converges to q, $\Phi_p(\widehat{apq})$ is defined as the limit of the sequence $\Phi_p(\widehat{apq}_p)$ (See [5] in details).

The function Φ_p thus defined fulfills the conditions $1^{\circ}, 2^{\circ}$, and 3° in § 2. The definition of the function Φ_p does not depend on any choice of the line \mathfrak{g}_p . In such a way we define the function Φ_p at every point p of \mathfrak{S} . Then we denote by Φ the function Φ_p . The angular measure Φ thus obtained is invariant under the reflections with respect to lines.

In the remainder of this note, by means of the angular measure Φ , we study a G-space with constant curvature. For the angle between two segments T(p, a) and T(p, b) we use the same notation $\stackrel{\wedge}{apb}$ as in § 2.

(3.1) Theorem. The angular measure Φ is continuous.

PROOF. Let $\{p_{\nu}\}$ be a sequence of points which converges to a point p, and put $\alpha = \inf \delta(p_{\nu})/2$. Then α is positive. Let D_{ν} be any sector of each $\overline{S(p_{\nu},\alpha)}$ such that Fl D_{ν} coincides with a sector D of $S(p,\alpha)$. Then the legs $T_{1\nu}$ and $T_{2\nu}$ of each D_{ν} tends to the legs T_1 and T_2 of D respectively. Let $q_{i\nu}$ be the end point of each $T_{i\nu}$ and q_i the end point of $T_i(i=1,2)$. Now we prove $\lim_{\nu\to+\infty} q_{1\nu}\hat{p}_{\nu}q_{2\nu} = q_1\hat{p}q_2$.

Obviously the sequences of points $\{q_{1\nu}\}$ and $\{q_{2\nu}\}$ converge to the points q_1 and q_2 respectively. Let each $q'_{2\nu}$ be a point on $K(p_{\nu}, \alpha)$ such that $q_{1\nu} \stackrel{\wedge}{p}_{\nu} q'_{2\nu} = q_1 \stackrel{\wedge}{p} q_2$. If we choose suitably such points $q'_{2\nu}$, then the sequence of points $\{q'_{2\nu}\}$ converges to q_2 . Suppose that such points $q'_{2\nu}$ have been chosen. Then there exists a positive integer N such that $S(p, \delta(p)) \supset S(p_{\nu}, \alpha)$ for every $\nu \geq N$. Since the angles $q'_{2\nu} \stackrel{\wedge}{p}_{\nu} q_{1\nu} (\nu \geq N)$ are invariant under the reflections with respect to lines which intersect $S(p, \delta(p))$, it follows that, if

⁷⁾ Let x and x' be two points on $K(p, \bar{\delta}(p))$. The open segment T(x, x') - x - x' is said a line \mathfrak{g}_p .

⁸⁾ A line g_p is said perpendicular to a set E at a point f, if every point on g_p has f as a foot on E.

for a positive number δ , N is sufficiently large, then $q_{2\nu}p_{\nu}q_{2\nu}<\delta$ for every $\nu\geq N$. Hence we have

$$\begin{aligned} |q_{1\nu}\hat{p}_{\nu}q_{2\nu} - q_{1}\hat{p}q_{2}| &= |q_{1\nu}\hat{p}_{\nu}q_{2\nu} - q_{1\nu}\hat{p}_{\nu}q_{2\nu}'| \\ &\leq q_{2\nu}'\hat{p}_{\nu}q_{2\nu} < \delta \qquad \text{for every } \nu \geq N. \end{aligned}$$

Thus the theorem is proved.

Making use of the angular measure Φ we define the excess function F. Then, by (2.4) and (3.1), we have the following:

(3.2) If the excess function F is of bounded variation, then F is continuous.

Under the assumption of (3.2), for any bounded subset X there exist a positive integer M and a positive number δ_0 such that every circular disk $\overline{S(p,\gamma)}(p\in X,\ 0<\gamma\leqq\delta_0)$ is covered by M circular disks with radius $\gamma/5$. Next we shall show this.

Let V be a bounded and connected open set which contains X. If we put $\delta = \inf_{x \in V} \delta(x)$, then δ is positive. Let δ_0 be a positive number not greater than δ . Let a line \mathfrak{g}_p through $p \in X$ intersect a sphere $K(p,\gamma)$ ($0 < \gamma \le \delta_0$) at points a and a' and a' and a' and a' and a' and length aa'/24 = bb'/24. If δ_0 is sufficiently small, then the lines perpendicular to a' and a' and a' and a' are composed of a' and a' and a' are points of the subdivisions form the net composed of a' quadrilaterals a'. This is clear from the continuity of the function a'.

For any circular disk $S(q, \delta_0)$ ($q \in X$) there exists the combination of finite number of reflections with respect to lines by which $S(p, \delta_0)$ is carried onto it. Hence if we put $M = 24^2$, then M and δ_0 are the numbers which fulfill the condition described above.

Let E be a set contained in a neighborhood $S(x, \delta(x))$. The parameter of regularity $\gamma(E)$ of E is defined as the upper bound of the number $\mu(E)/\mu(\overline{S})$, where \overline{S} denotes any circular disk containing E. Let $\{E_{\nu}\}$ be a sequence of closed sets on $\mathfrak S$ which tends to a point p. If there exists a positive number α such that $\gamma(E_{\nu}) \geq \alpha(\nu = 1, 2, \ldots)$, then the sequence $\{E_{\nu}\}$ is said to be regular.

Let \mathfrak{F} be a family of closed sets such that the parameter of regularity of each set exceeds a fixed number $\alpha(>0)$ and for every point x of the set X there exists in \mathfrak{F} a regular sequence of sets $\{W_{\nu}\}$ $(W_{\nu} \ni x)$ which tends to x. Then \mathfrak{F} contains a finite or countable sequence $\{X_{\nu}\}$ of sets no two of which have common points, such that

$$(3.3) \qquad \mu(X - \sum X) = 0.$$

Next we prove (3.3). To do this, we suppose that every set of \mathfrak{F} can be covered by a circular disk with radius not greater than $\delta_0/5$.

Choose an arbitrary set X_1 of \mathfrak{F} and suppose that the first λ sets X_1 , X_2 , ..., X_{λ} no two of which have common points have been chosen. If X —

 $\sum_{\nu=1}^{\lambda} X_{\nu} = \phi$, then the theorem is proved. If this is not so, we denote by δ_{λ} the upper bound of the diameters of all sets which have no common points with $\sum_{\nu=1}^{\lambda} X_{\nu}$ and choose an arbitrary set $X_{\lambda+1}$ of those sets with diameter exceeding $\delta_{\lambda}/2$. If $X - \sum_{\nu=1}^{\lambda+1} X_{\nu} \neq \phi$, then we continue this process. Suppose that an infinite sequence of sets $\{X_{\nu}\}$ has been chosen, and put

Suppose that an infinite sequence of sets $\{X_{\nu}\}$ has been chosen, and put $Y = X - \sum_{\nu=1}^{\infty} X_{\nu}$. It is sufficient to show that, if $\mu(Y) > 0$, then we arrive at a contradiction. To do this, associate with each set X_{ν} a circular disk \overline{S}_{ν} with radius γ_{ν} such that $X_{\nu} \subset \overline{S}_{\nu}$ and $\mu(X_{\nu})/\mu(\overline{S}_{\nu}) > \alpha/2$, and let \overline{S}'_{ν} be the circular disk with the same center as \overline{S}_{ν} and the radius $5\gamma_{\nu}$. We then have

(3.4)
$$\sum_{\nu=1}^{\infty} \mu(\overline{S}'_{\nu}) < M \sum_{\nu=1}^{\infty} \mu(\overline{S}_{\nu}) \leq 2M\alpha^{-1} \sum_{\nu=1}^{\infty} \mu(X_{\nu}) < + \infty.$$

Hence a positive integer N exists such that $\sum_{\nu=N+1}^{\infty} \mu(\overline{S_{\nu}}) < \mu(Y)$. From this it follows that there exists a point $x_0 (\in X)$ not belonging to $\sum_{\nu=N+1}^{\infty} S'_{\nu}$. By virtue of the assumption there must exist a set $X' (\ni x_0)$ of $\widetilde{\mathfrak{F}}$ such that $X' \cap X_{\nu} = \phi$ for $\nu=1,2,\ldots,N$. From (3.4) we see that the radius γ_{ν} of $\overline{S_{\nu}}$ tends to zero as $\nu \to +\infty$. Hence X' has common points with at least one of the sets X_{ν} ($\nu > N$). Let ν_0 be the smallest integer such that $X' \cap X_{\nu_0} \neq \phi$. The diameter of X' does not exceed $\delta_{\nu_0-1} (< 4 \gamma_{\nu_0})$. Hence $X' \subset \overline{S'_{\nu_0}}$, which contradicts to the assumption $x_0 \in \sum_{\nu=1}^{\infty} \overline{S'_{\nu}}$. Thus (3.3) is proved.

By use of (3.3) it is easily proved that Vitali's Covering Theorem holds on \mathfrak{S} , i.e., if a set X is covered by a family \mathfrak{F} of closed sets in the sense of Vitali, there exists in \mathfrak{F} a finite or countable sequence $\{X_{\nu}\}$ of sets no two of which have common points such that (3.3) holds. For any subset Z there exists a $(G)_{\mathfrak{F}}$ set G such that $Z \subset G$ and $\mu(Z) = \mu(G)$. By virtue of this property and Vitali's Covering Theorem it is easily seen that the additive function of a set F^* is derivable at almost all points [3]. Taking account of the reflection with respect to lines, F is derivable at every point and its derivative is equal to a constant number 1/k. Hence the excess function F is derivable at every point, i.e., for any regular sequence of normal triangles $\{\sigma_{\nu}\}$ which tends to a point $p \lim_{\nu \to +\infty} F(\sigma_{\nu})/\mu(\sigma_{\nu})$ exists and is equal to 1/k. Next we prove the following

(3.5) Theorem. If the excess function F is of bounded variation, then F is absolutely continuous and its derivative is equal to a constant number 1/k. For any normal triangle $\sigma(=abc)$ the function F is given by

$$\mu(\sigma)/k = \hat{bac} + \hat{cba} + \hat{acb} - \pi.$$

PROOF. It is sufficient to prove that the function T^* of signilarities of F^* vanishes on \mathfrak{S} . It is easy to see that the derivative of the function T^* is equal to zero at every point. We prove the theorem only in the case where the function T^* is non-negative, since its upper and lower variations are

finite.

Let p be any point on \mathfrak{S} , and put $m\delta = \delta(p)$, where m is a positive integer. Let a line \mathfrak{g}_p through p intersect $K(p,\delta)$ at points a and a' and \mathfrak{h}_p and \mathfrak{h}_p' be the supporting lines of $K(p,\delta)$ at a and a' respectively. Then \mathfrak{g}_p divides $S(p,\delta(p))$ into two domains. We denote by D one of these domains.

Let $\{p_{\nu}\}$ and $\{p'_{\nu}\}$ be the sequence of points in D such that $p_{\nu} \in E[\mathfrak{h}_{p}]$, $p'_{\nu} \in E[\mathfrak{h}_{p}']$, and $ap_{\nu} = a'p'_{\nu} = \delta/2^{\nu}$ for each ν and $\mathfrak{g}_{\nu,\nu}$ the line which contains each $T(p_{\nu}, p'_{\nu})$ as a subsegment. Then

$$\mathfrak{g}_{p,\nu} \cap \mathfrak{g}_p = \phi \qquad \text{for every } \nu.$$

Next we subdivide the segment T(a, a') by points $a_{\nu}^{(1)}$, $a_{\nu}^{(2)}$, ..., $a_{\nu}^{(\bar{\nu})}$ as follows:

Take on \mathfrak{g}_{ν} the point $a_{\nu}^{(1)}$ such that $aa_{\nu}^{(1)} = ap_{\nu}$ and let $p_{\nu}^{(1)}$ be the point at which the line perpendicular to \mathfrak{g}_{p} at $a_{\nu}^{(1)}$ intersects the line $\mathfrak{g}_{p,\nu}$. Further take on \mathfrak{g}_{p} the point $a_{\nu}^{(2)}$ such that $a_{\nu}^{(1)}a_{\nu}^{(2)} = a_{\nu}^{(1)}p_{\nu}^{(1)}$. Then we can determine the point $p_{\nu}^{(2)}$ as above. If $a_{\nu}^{(1)}a' \leq a_{\nu}^{(1)}p_{\nu}^{(1)}$, we end this process. If $a_{\nu}^{(1)}a' > a_{\nu}^{(1)}p_{\nu}^{(1)}$, then we continue this process. On account of (3.6), after finite steps we arrive at a point $a_{\nu}^{(\bar{\nu})}$ such that $a_{\nu}^{(\bar{\nu})}a' \leq a_{\nu}^{(\bar{\nu})}p_{\nu}^{(\bar{\nu})}$ and $a_{\nu}^{(\bar{\nu})} \in E[T(a,a')]$. Then we take on \mathfrak{g}_{p} and $\mathfrak{g}_{p,\nu}$ the points $a_{\nu}^{(\bar{\nu}+1)}$ and $p_{\nu}^{(\bar{\nu}+1)}$ in the same way as above respectively.

Thus we have $\bar{\nu}+1$ quadrilaterals $a_{\nu}^{(i)}a_{\nu}^{(i+1)}p_{\nu}^{(i)}(i=0,1,2,\ldots)$ for each ν , where $a_{\nu}^{(0)}=a$. We denote by $P_{\nu}^{(i)}$ each quadrilateral $a_{\nu}^{(i)}a_{\nu}^{(i+1)}p_{\nu}^{(i+1)}p_{\nu}^{(i)}$. By virtue of the continuity of the function F, each inside angle of $P_{\nu}^{(i)}$ tends to $\pi/2$ as $\nu\to+\infty$. Hence it follows that for every point x of T(a,a') there exists a regular sequence of quadrilaterals $\{P_{\nu}^{(i\nu)}\}(P_{\nu}^{(i\nu)}\ni x)$ tending to x.

Now we prove that for an arbitrary positive number ε there exists a positive integer N such that

(3.7)
$$T^*(P_{\nu}^{(i\nu)}) < \varepsilon \mu(P_{\nu}^{(i\nu)}) \text{ for each } \nu \ge N \text{ and each } i \ (0 \le i \le \bar{\nu}).$$

If this is not so, then we should have a sequence of positive integers $\{\lambda\}$ $(\subset \{\nu\})$ such that

(3.8)
$$T^*(P_{\lambda}^{(i_{\lambda})}) \ge \varepsilon \mu(P_{\lambda}^{(i_{\lambda})})$$

for each λ and a positive integer i_{λ} $(0 \le i_{\lambda} \le \tilde{\lambda})$. Let $\mathfrak{h}_{p,\lambda}$ be the line perpendicular to \mathfrak{g}_p at the midpoint of the segment $T(a,a_{\lambda}^{(i\lambda)})$. Then $a_{\lambda}^{(i\lambda)}$ $\Omega(\mathfrak{h}_{p,\lambda})=a$. Hence each quadrilateral $P_{\lambda\lambda}^{(i)}$ is carried by $\Omega(\mathfrak{h}_{p,\lambda})$ onto a quadrilateral $P_{\lambda}^{(i)}$ with the vertex a. The sequence of quadrilaterals $\{P_{\lambda}^{(i)}\}$ is regular and tends to a. Hence there exists a positive integer N' such that

$$T^*(P'_{\lambda}) < \mathcal{E}\mu(P'_{\lambda})$$
 for every $\lambda \ge N'$.

Obviously $T^*(P_{\lambda}^{(i\lambda)}) = T^*(P_{\lambda}')$ and $\mu(P_{\lambda}^{(i\lambda)}) = \mu(P_{\lambda}')$ for every λ , but this contradicts to (3.8). Thus (3.7) is proved.

Between the lines \mathfrak{g}_p and $\mathfrak{g}_{p,N}$, there exist $\overline{N}+1$ quadrilaterals $P_N^{(0)}, P_N^{(1)}$, ..., and $P_N^{(\overline{N})}$ which fulfill the condition (3.7). We put

$$\overline{P}_N^{(i)} = P_N^{(i)} \Omega(\mathfrak{g}_{p,N}) \qquad (i = 0, 1, 2, \ldots, N).$$

Then it is easy to see that the two vertices of each $\overline{P}_N^{(i)}$ lie on the line $\mathfrak{g}_p\Omega(\mathfrak{g}_{p,N})$. Hence, in such a way, we get the figure R composed of a finite number of non-overlapping quadrilaterals P_{ν} such that $S(p,\delta(p))\supset R\supset S(p,\delta)$ for a sufficiently large positive integer m and each P_{ν} fulfills the condition (3.8). The figure R is expressed as the sum $\sum P_{\nu}$. From this it follows that

$$T^*(S(p, \delta)) < T^*(R) = \Sigma T^*(P_{\nu})$$

 $< \varepsilon \Sigma \mu(P_{\nu})$
 $= \varepsilon \mu(R), \text{ and}$
 $\mu(R) > \mu(S(p, \delta)).$

Therefore we conclude that $T^*(S(p, \delta)) = 0$, since ε is arbitrary. From this we see that T^* vanishes on \mathfrak{S} . Thus the theorem is proved.

4. Let \mathfrak{G} be a G-space with constant curvature and of dimension $n \geq 2$ and $\widehat{\mathfrak{G}}$ the universal covering space of \mathfrak{G} . In a subspace of dimension (n-1) of $\widehat{\mathfrak{G}}$ the bisector of any two distinct points is linear and of dimension (n-2). We call this a subspace of dimension (n-2). Repeating this, in a subspace of dimension 2, the bisector of any two distinct points is an extremal [5].

The generalized Gaussian curvature of every subspace of dimension 2 is equal to a constant number 1/k. If G is Riemannian, then the number 1/k is its Riemannian curvature. The number 1/k will be said the generalized Riemannian curvature of 6.

(4.1) Theorem. If the space $^{(5)}$ is of type I, then its generalized Riemannian curvature is positive.

PROOF. In $\widetilde{\mathfrak{G}}$, every subspace $\widetilde{\mathfrak{S}}$ of dimension 2 is compact and covered by a finite number of triangles $\sigma_i(i=1,2,\ldots,m)$. From (2.4) it tollows that

$$\sum_{i=1}^m F(\sigma_i) = 4\pi$$

since $\chi(\widetilde{\mathfrak{S}}) = 2$. Therefore we have by (3.5)

$$\sum_{i=1}^m \mu(\sigma_i)/k = 4\pi.$$

Since $\sum_{i=1}^{m} \mu(\sigma_i) = \mu(\widetilde{\mathfrak{S}}) > 0$, the number 1/k is positive. Thus the theorem is proved.

On § the following properties can easily be proved by classical arguments.

(4.2) (i) Let abc be a rectangular triangle with $acb = \pi/2$ and m(a, b) the midpoint of the segment T(a, b). Then the distance between m(a, b) and

E[T(b,c)] is greater than the half of ac. (ii) Every equidistant curve to an extremal $\mathfrak x$ turns its convexity toward $\mathfrak x$. (iii) For an extremal subarc $\mathfrak x(\tau)$, $\alpha \le \tau \le \beta$, and an extremal $\mathfrak x$, the function $f(\tau) = \mathfrak x(\tau) E[\mathfrak x]$ ($= \inf_{z \in E[\mathfrak x]} \mathfrak x(\tau) \mathfrak x$) is a concave function.

Next we prove the following

(4.3) THEOREM. If the space § is of Type II, then its generalized Riemannian curvature is non-positive.

PROOF. It is sufficient to prove that, if 1/k is positive, we arrive at a contradiction. Let $\widetilde{\mathfrak{S}}$ be a subspace of dimension 2 of $\widetilde{\mathfrak{S}}$, and let p be any point on $\widetilde{\mathfrak{S}}$ and f the foot of p on an extremal $\mathfrak{x}(\ni p)$. Further let $\mathfrak{x}(\tau), -\infty < \tau < +\infty$, be the parametric representation of \mathfrak{x} such that $\mathfrak{x}(0) = f$ and τ_0 a fixed positive number. Then, for any positive number $\tau(>\tau_0)$, we have by putting $\mathfrak{x}(\tau) = b$ and $\mathfrak{x}(-\tau) = b'$

(4.4)
$$\mu(pbb')/k = p\hat{b}b' + p\hat{b}'b - (\pi - b\hat{p}b') \\ > \mu(paa')/k,$$

where $x(\tau_0) = a$ and $x(-\tau_0) = a'$. We can easily see that, on \mathfrak{S} , for any positive number ε there exist two positive numbers α and β such that, for any three points x, y and z which satisfy the conditions $xy = xz = \alpha$ and $yz \ge 2\alpha(1-\beta)$, the inequality $yxz \ge \pi - \varepsilon/2$ holds.

Assume that $\mu(paa') > k\varepsilon > 0$, and put $\lambda(\tau) = pb \ (= px(\tau))$ and $2\beta = \delta$. The function $f(\tau) = \lambda(\tau) - \tau + \delta \tau$ is continuous on the interval $\tau_0 \le \tau < +\infty$, and $\lim_{\tau \to +\infty} f(\tau) = +\infty$. Hence $f(\tau)$ attains its minimum at some value τ on $\tau_0 \le \tau < +\infty$ and fulfills the condition

$$\lambda(\overline{\tau} + \sigma) - (\overline{\tau} + \overline{\sigma}) + \delta(\tau + \sigma) - \{\lambda(\tau) - \overline{\tau} + \delta\overline{\tau}\} \ge 0 \text{ for } \sigma \ge 0.$$
 Therefore

$$(4.5) \lambda(\tau + \sigma) - \lambda(\tau) \ge \sigma(1 - \delta).$$

Put $c = x(\tau)$ and $c' = x(-\tau)$, and let d and e be the points on T(p,c) and on the prolongation of the segment T(f,c) respectively such that $cd = ce = \alpha$. If we put $\sigma = \alpha$ in (4.5), we then have

$$de \ge 2 \alpha (1 - \beta)$$

since $de - \alpha > \lambda(\tau + \alpha) - \lambda(\tau)$. Hence we see $pcd \ge \pi - \varepsilon/2$. Let d' be the point on the prolongation of the segment T(f,c') such that $c'd' = \alpha$. Then we see $p\hat{c}'d' = \pi - \varepsilon/2$ since on $\widetilde{\mathfrak{S}}$ the bisector property holds in the large. On the other hand $\pi - c\hat{p}c' \ge 0$ is obvious. Hence we see from (4.4)

$$\begin{split} \mu(p\hat{a}a')/k &< \mu(p\hat{c}c')/k \leq \hat{p}cc' + p\hat{c}c' \\ &= (\pi - \hat{p}cd) + (\pi - p\hat{c}d') \\ &\leq \varepsilon/2 + \varepsilon/2 = \varepsilon, \end{split}$$

which contradicts to the assumption $0 < k\mathcal{E} < \mu(paa')$. Thus the theorem is proved.

If the number 1/k is equal to zero, then $\widetilde{\mathfrak{S}}$ has the same property as a

euclidean plane, i.e., the theorem in plane geometry holds on $\widetilde{\mathfrak{S}}$. We can introduce Lebesgue measure which coincides with Hausdorff measure μ . If 1/k < 0, then the following properties of $\widetilde{\mathfrak{S}}$ is also easily proved by classical arguments.

(4.6) (i) Let abc be a rectangular triangle with $acb = \pi/2$ and m(a, b) the midpoint of the segment T(a, b). Then the distance between m(a, b) and E[T(b, c)] is less than the half of ac. (ii) Every equidistant curve to an extremal $\mathfrak x$ turns its concavity toward $\mathfrak x$. (iii) For an extremal subarc $\mathfrak x(\tau)$, $\alpha \le \tau \le \beta$, and an extremal $\mathfrak x$ the function $f(\tau) = \mathfrak x(\tau)E[\mathfrak x]$ is a convex function.

In virtue of (3.5), (4.1), (4.2), (4.3) and (4.6), if \mathfrak{G} is a G-space with constant curvature and the excess function is of bounded variation, the space \mathfrak{G} is of Type I or Type II according as its constant generalized Riemannian curvature is positive or non-positive. Specially, if 1/k = 0, the space $\widetilde{\mathfrak{G}}$ is regarded as an n-dimensional euclidean space.

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