# ON ALMOST-ANALYTIC VECTORS IN CERTAIN ALMOST-HERMITIAN MANIFOLDS ${ }^{1 \text { }}$ 

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0. Introduction. On an $n$-dimensional differentiable manifold $M$ with local coordinate systems $\left\{x^{i}\right\}^{2)}$, a tensor field $\boldsymbol{\varphi}_{j}{ }^{i}$ of type $(1,1)$ such that

$$
\begin{equation*}
\boldsymbol{\varphi}_{r}{ }^{i} \boldsymbol{\varphi}_{j}{ }^{r}=-\delta_{j}{ }^{i} \tag{0.1}
\end{equation*}
$$

is called an almost-complex structure. It is a well known fact ${ }^{3)}$ that a manifold $M$ with an almost-complex structure $\boldsymbol{\varphi}_{j}{ }^{i}$ always admits a positive definite Riemannian metric tensor $g_{j i}$ such that
$g_{r s} \boldsymbol{\varphi}_{j}{ }^{r} \boldsymbol{\varphi}_{i}{ }^{s}=g_{j i}$.
The pair ( $\boldsymbol{\varphi}_{j}{ }^{i}, g_{j i}$ ) satisfying ( 0.1 ) and ( 0.2 ) is called an almost-Hermitian structure and the manifold $M$ with the structure ( $\boldsymbol{\varphi}_{j}{ }^{i}, g_{j i}$ ) is called an almostHermitian manifold.

Let $M$ be an almost-Hermitian manifold, then a differential form $\boldsymbol{\varphi}=$ $\boldsymbol{\varphi}_{j i} d x^{j} d x^{i}$, where $\boldsymbol{\varphi}_{j i}=\boldsymbol{\varphi}_{j}{ }^{r} g_{r i}$, is associated to the structure. If the form $\boldsymbol{\varphi}$ is closed, the structure is called an almost-Kählerian structure. In this case, the tensor $\boldsymbol{\varphi}_{j t}$ is harmonic of order two.

On the other hand, A. Frölicher ${ }^{4}$ proved that there exists an almostcomplex structure on the six dimensional sphere $S^{6}$. And T. Fukami and S . Ishihara ${ }^{5}$ ) proved that the structure on $S^{6}$ is an almost-Hermitian one satisfying the following relation

$$
\begin{equation*}
\nabla_{k} \boldsymbol{\varphi}_{j i}+\nabla_{j} \boldsymbol{\varphi}_{k i}=0, \tag{0.3}
\end{equation*}
$$

where and throughout this paper $\nabla_{k}$ denotes the operator of covariant derivative with respect to the Riemannian connection.

The last equation expresses the fact that the tensor $\boldsymbol{\varphi}_{j i}$ is a Killing tensor of order two. ${ }^{6)}$

In my previous paper, ${ }^{7)}$ I treated almost-analytic vectors in almost-

[^0]Kählerian manifolds. By an analogous method we shall discuss about almostanalytic vectors in almost-Hermitian manifolds in which the equation (0.3). is valid. After preliminaries in $\S 1$, we shall introduce in $\S 2$ almost-analytic vectors in our manifold. In $\S 3$ it will be obtained a necessary condition in order that a vector $v$ is a contravariant almost-analytic vector. Similarly $\S 4$ is devoted to covariant almost-analytic vectors. In $\S 5$ and $\S 6$, integral formulas will be obtained in the case where our manifold is compact.

1. Preliminaries. In this paper, by $M$ we shall always mean an $n$ dimensional differentiable manifold with a fixed almost-Hermitian structure( $\varphi_{j}^{r i}, g_{j i}$ ) such that

$$
\begin{equation*}
\nabla_{k} \boldsymbol{\varphi}_{j i}+\nabla_{j} \boldsymbol{\varphi}_{k i}=0, \tag{1.1}
\end{equation*}
$$

where $\boldsymbol{\varphi}_{j t}=\boldsymbol{\varphi}_{j}{ }^{r} g_{r i}$. We shall call such a manifold $K$-space, for convenience.

By (0.1) and (0.2), $\boldsymbol{\varphi}_{j i}$ is skew symmetric with respect to $j$ and $i$. By, (1. 1), $\nabla_{k} \varphi_{j i}$ is also skew symmetric with respect to all indices.

Transvecting (1.1) with $g^{j i}$, it follows that

$$
\begin{equation*}
\nabla^{r} \boldsymbol{\varphi}_{r i}=0 \tag{1.2}
\end{equation*}
$$

In this section we shall use (1.2) but shall not use (1.1), so the results: which will be obtained in this section are true in almost-Hermitian manifolds. with the relation (1.2).

Let $R_{k j t}{ }^{h}$ be the Riemannian curvature tensor i. e.

$$
R_{k j i}^{h}=\partial_{k}\left\{\begin{array}{l}
h j
\end{array}\right\}-\partial_{j}\left\{\begin{array}{l}
h \\
k i
\end{array}\right\}+\left\{\begin{array}{l}
h \\
k r
\end{array}\right\}\left\{\begin{array}{l}
r \\
\{j i
\end{array}\right\}-\left\{\begin{array}{l}
h \\
j r
\end{array}\right\}\left\{\begin{array}{l}
r \\
k i
\end{array}\right\},
$$

where $\partial_{i}=\partial / \partial x^{i}$, and put

$$
R_{j i}=R_{r j i}{ }^{r}, \quad R_{k j i h}=R_{k j i}{ }^{r} g_{r h}
$$

and

$$
\begin{equation*}
R_{k j}^{*}=\frac{1}{2} \boldsymbol{\phi}^{p q} R_{p q i j} \boldsymbol{\varphi}_{k}{ }^{i}, \tag{1.3}
\end{equation*}
$$

where $\boldsymbol{\phi}^{p q}=\boldsymbol{\varphi}_{r}{ }^{q} g^{r p}$.
Applying the Ricci's identity to $\boldsymbol{\varphi}_{\mathbf{t}}{ }^{h}$, we obtain the identity

$$
\nabla_{k} \nabla_{j} \varphi_{i}{ }^{h}-\nabla_{j} \nabla_{k} \varphi_{i}{ }^{h}=R_{k j r}{ }^{h} \boldsymbol{\varphi}_{i}{ }^{r}-R_{k j i}{ }^{r} \boldsymbol{\varphi}_{r}{ }^{h} .
$$

Transvecting the last equation with $g^{j i}$ and using (1.2), we find

$$
\nabla^{r} \nabla_{j} \boldsymbol{\varphi}_{r}{ }^{h}=R_{k j r}{ }^{h} \boldsymbol{\varphi}^{k r}+R_{j}^{r} \boldsymbol{\varphi}_{r}{ }^{h} .
$$

As $\phi^{k r}$ is skew symmetric with respect to $k$ and $r$, we get

$$
\nabla^{r} \nabla_{j} \boldsymbol{\varphi}_{r}{ }^{n}=\frac{1}{2} \boldsymbol{\varphi}^{p q} R_{p q j}{ }^{n}+R_{j}^{r} \boldsymbol{\varphi}_{r}^{n},
$$

from which we obtain

$$
\begin{equation*}
\nabla^{r} \nabla_{j} \boldsymbol{\varphi}_{r h}=\frac{1}{2} \boldsymbol{\varphi}^{p q} R_{p a j h}+R_{j}^{r} \boldsymbol{\varphi}_{r h} . \tag{1.4}
\end{equation*}
$$

A vector field $v$ is called a contravariant almost-analytic vector or simply an analytic vector if its contravariant components satisfy the equations

$$
\begin{equation*}
\underset{v}{£} \boldsymbol{\varphi}_{j}{ }^{i} \equiv v^{r} \nabla_{r} \varphi_{j}{ }^{i}-\varphi_{j}^{r} \nabla_{r} v^{i}+\varphi_{r}{ }^{i} \nabla_{j} v^{r}=0, \tag{1.5}
\end{equation*}
$$

where $\underset{v}{£}$ is the operator of Lie derivative.
A vector field $u$ is called a covariant almost-analytic vector or simply a covariant analytic vector if its covariant components satisfy the equations

$$
\begin{equation*}
\nabla_{j}\left(\boldsymbol{\varphi}_{i}^{r} u_{r}\right)=u_{r} \nabla_{i} \boldsymbol{\varphi}_{j}^{r}+\boldsymbol{\varphi}_{j}{ }^{r} \nabla_{r} u_{i} \tag{1.6}
\end{equation*}
$$

LEMMA 1. 1. ${ }^{8)}$ In a compact almost-Hermitian manifold $M$ in which the equation (1.2) is valid, if scalar functions $f$ and $g$ satisfy the equation

$$
\nabla_{i} f=\varphi_{i}^{r} \nabla_{r} g
$$

then the functions are both constant over $M$.
Let $v$ be an analytic vector, $u$ a covariant analytic vector and put

$$
g=u_{l} v^{l} \text { and } f=\varphi_{r}{ }^{l} u_{l} v^{r}
$$

then by virtue of Lemma 1. 1 and definitions, we get easily the following
THEOREM 1. 2. In a compact almost-Hermitian manifold $M$ in which the equation (1.2) is valid, the inner product of an analytic vector and a covariant analytic vector is constant over the whole $M$.

From (1. 6) we have

$$
\begin{equation*}
\left(\nabla_{j} \varphi_{i}^{r}-\nabla_{i} \varphi_{j}^{r}\right) u_{r}=\varphi_{j}^{r} \nabla_{r} u_{i}-\boldsymbol{\varphi}_{i}^{r} \nabla_{j} u_{r} \tag{1.7}
\end{equation*}
$$

for a covariant analytic vector $u$. And again from (1.6) we have

$$
\begin{equation*}
\nabla_{j}\left(\boldsymbol{\varphi}_{i}^{r} u_{r}\right)=\nabla_{i}\left(\boldsymbol{\varphi}_{j}{ }^{r} u_{r}\right)-\boldsymbol{\varphi}_{j}^{r} \nabla_{i} u_{r}+\boldsymbol{\varphi}_{j}{ }^{r} \nabla_{r} u_{i} . \tag{1.8}
\end{equation*}
$$

Now we shall define a vector field $\bar{u}$ by the equation

$$
\bar{u}_{i}=\phi_{i}{ }^{t} u_{t}
$$

for any vector field $u$, then it is equivalent to define

$$
\tilde{u}^{i}=-\boldsymbol{\varphi}_{t}{ }^{i} u^{t}
$$

Thus (1. 8) becomes the following form :

$$
\begin{equation*}
\nabla_{j} \bar{u}_{i}-\nabla_{i} \bar{u}_{j}=\varphi_{j}^{r}\left(\nabla_{r} u_{i}-\nabla_{i} u_{r}\right)^{9)} \tag{1.9}
\end{equation*}
$$

The equations (1.6), (1.7) and (1.9) are equivalent to each other.

[^1]By transvection (1.6) with $g^{j i}$ we get easily

$$
\begin{equation*}
\nabla^{r} \bar{u}_{r}=0 \tag{1.10}
\end{equation*}
$$

By virtue of (1.9) and (1.10) we have
Theorem 1. 3. In an almost-Hermitian manifold $M$ in which the equation (1.2) is valid, if a covariant analytic vector $u$ is closed i.e. $\nabla_{j} u_{i}=\nabla_{i} u_{j}$, then $\bar{u}$ is harmonic.
2. Identities. In the following we suppose that the manifold $M$ is always a $K$-space, that is, (1. 1) holds good.

From (1. 1) and (1. 4), we get directly

$$
\begin{equation*}
\nabla^{r} \nabla_{r} \boldsymbol{\varphi}_{j i}=-\frac{1}{2} \boldsymbol{\varphi}^{p a} R_{p q j i}-R_{j}^{r} \boldsymbol{\varphi}_{r i} . \tag{2.1}
\end{equation*}
$$

If we notice the skew symmetry with respect to $j$ and $i$ in (2. 1), we see that

$$
R_{j}^{r} \boldsymbol{\varphi}_{r i}+R_{i}^{r} \boldsymbol{\varphi}_{r j}=0
$$

from which we get

$$
\begin{equation*}
R_{r s} \boldsymbol{\varphi}_{j}^{r} \boldsymbol{\varphi}_{i}^{s}=R_{j i} . \tag{2.2}
\end{equation*}
$$

In the next place, from (1.1) we have

$$
\nabla_{k} \boldsymbol{\varphi}_{j i}=\nabla_{i} \boldsymbol{\varphi}_{k j}
$$

Transvecting the last equation with $\boldsymbol{\varphi}^{k j}$ and taking account of (0.1) and (0.2), we find

$$
\left(\nabla_{k} \varphi_{j i}\right) \varphi^{k j}=0
$$

If we operate $\nabla_{r}$ to the last equation, then we have easily

$$
\left(\nabla_{i} \varphi_{k j}\right) \nabla_{r} \varphi^{k j}=-\left(\nabla_{r} \nabla_{k} \varphi_{j i}\right) \varphi^{k j}
$$

By the Ricci's identity and skew symmetry of $\varphi^{k j}$, after some calculation, we get

$$
\begin{equation*}
\left(\nabla_{i} \boldsymbol{\varphi}_{k j}\right) \nabla_{r} \varphi^{k j}=R_{r i}^{*}-2 R_{i r}^{*}+R_{r i}, \tag{2.3}
\end{equation*}
$$

where $R_{k_{j}}^{*}$ is defined by (1.3). As the left hand side is symmetric with respect to $i$ and $r$, we see that

$$
\begin{equation*}
R_{i r}^{*}=R_{r i}^{*} \tag{2.4}
\end{equation*}
$$

holds good. Consequently (2.3) becomes
(2. 5)

$$
\left(\nabla_{i} \boldsymbol{\varphi}_{k j}\right) \nabla_{r} \varphi^{k j}=R_{i r}-R_{i r}^{*}
$$

Hence we have
THEOREM 2. 1. In a $K$-space $M$, the inequality

$$
R_{j i} v^{j} v^{i} \geqq R_{j i}^{*} v^{j} v^{i}
$$

is valid for any vector field $v$.
As an application of the last theorem, we shall give the following
THEOREM 2. 2. ${ }^{10}$ If $n \geqq 4$ and a $K$-space $M$ is conformally flat, then. the Ricci's quadratic form $R_{j i} v^{j} v^{i}$ can not be negative definite.

PRoof. From the assumption, the curvature tensor of $M$ has the following form ${ }^{11)}$

$$
\begin{aligned}
R_{k j i h} & =\frac{1}{n-2}\left(g_{k h} R_{j i}-g_{j h} R_{k i}+R_{k h} g_{j i}-R_{j h} g_{k i}\right) \\
& -\frac{R}{(n-1)(n-2)}\left(g_{k h} g_{j i}-g_{j h} g_{k i}\right) .
\end{aligned}
$$

Hence we have

$$
R_{j i}^{*}=\frac{1}{n-2}\left(2 R_{j i}-\frac{R}{n-1} g_{j i}\right)
$$

from which it follows that

$$
\begin{equation*}
R_{j i}-R_{j i}^{*}=\frac{1}{n-2}\left\{(n-4) R_{j i}+\frac{R}{n-1} g_{j i}\right\} . \tag{2.6}
\end{equation*}
$$

If the Ricci's quadratic form $R_{j i} v^{j} v^{i}$ is negative definite, then $R<0$. Hence(2. 6) contradicts to the Theorem 2. 1.

CORollary. If $n \geqq 4$, there does not exist a $K$-space of constant curvature with $R<0$.

The Nijenhuis' tensor of an almost-complex structure is defined by

$$
N_{j i}{ }^{h}=\varphi_{j}{ }^{l}\left(\nabla_{l} \varphi_{i}{ }^{h}-\nabla_{i} \varphi_{l}{ }^{h}\right)-\varphi_{i}{ }^{l}\left(\nabla_{l} \varphi_{j}{ }^{h}-\nabla_{j} \varphi_{l}{ }^{h}\right){ }^{11)}
$$

By virtue of (1.1), in $K$-space $M$, the last equation turns to

$$
N_{j i}{ }^{h}=-4 \varphi_{r}{ }^{h} \nabla_{j} \varphi_{i}{ }^{r} .
$$

If we put

$$
\begin{equation*}
N_{j i h}=N_{j i}{ }^{r} g_{r h} \tag{2.7}
\end{equation*}
$$

then it follows that

$$
N_{j i h}=-4\left(\nabla_{j} \varphi_{i}{ }^{r}\right) \boldsymbol{\varphi}_{r h} .
$$

It is easily seen that $N_{j i l}$ is skew symmetric with respect to all indices.
Let $v$ be a vector field and define $N(v)_{h}$ by the equation

$$
\begin{equation*}
N(v)_{h}=\frac{1}{4}\left(\Delta^{j} v^{i}\right) N_{j i h} \tag{2.8}
\end{equation*}
$$

10) If the manifold $M$ is compact, the theorem is a direct consequence of Theorem 4.2 in : p. 80 of K. Yano, and S. Bochner [6].
11) K. Yano [7].
where $\nabla^{j} v^{i}=g^{j r} \nabla r^{2} v^{i}$. Then, by virtue of (0.1), (0.2), (1.1) and (2.7), we have

$$
\begin{equation*}
N(\boldsymbol{v})_{h}=\left(\nabla^{j} v^{i}\right)\left(\nabla_{r} \boldsymbol{\varphi}_{j i}\right) \boldsymbol{\varphi}_{h}{ }^{r} \tag{2.9}
\end{equation*}
$$

In the next place we shall prepare a lemma which is useful in § 6.
From $\tilde{v}_{i}=\varphi_{i}{ }^{t} v_{t}$, we have

$$
\nabla^{r} \nabla_{r} \bar{v}_{i}=\left(\nabla^{r} \nabla_{r} \varphi_{i t}\right) v^{t}+2\left(\nabla^{\tau} \boldsymbol{\varphi}_{i}^{t}\right) \nabla_{r} v_{t}+\varphi_{i}^{t} \nabla^{r} \nabla_{r} v_{t} .
$$

Transvecting $\widetilde{v}^{i}=-\boldsymbol{\varphi}_{t}{ }^{i} v^{t}$ with the last equation and taking account of (1.1), (2.1), (2.2) and (2.9), we find

$$
\tilde{v}^{i} \nabla^{r} \nabla_{r} \tilde{v}_{i}=v^{i}\left\{\nabla^{r} \nabla_{r} v_{i}+R_{r i}^{*} v^{r}-R_{r i} v^{r}+2 N(v)_{i}\right\} .
$$

Hence we get the following equation

$$
\begin{align*}
\left(\nabla^{\tau} \nabla_{r} \widetilde{v}_{i}-R_{r i} \tilde{v}^{r}\right) \widetilde{v}^{i} & =\left(\nabla^{\tau} \nabla_{r} v_{i}-R_{r i} v^{r}\right) v^{i}  \tag{2.10}\\
& +\left\{2 N(v)_{i}-\left(R_{r i}-R_{r i}^{*}\right) v^{r}\right\} v^{i} .
\end{align*}
$$

On the other hand, the following theorem is well known. ${ }^{12)}$
In a compact orientable Riemannian manifold $V_{n}$, the integral formula

$$
\int_{\nabla_{n}}\left[\left(\nabla^{r} \nabla_{r} u_{i}-R_{r i} u^{r}\right) u^{i}+S(u)\right] d \sigma=0
$$

is valid for any vector field $u$, where $S(u)$ is given by

$$
S(u)=\frac{1}{2}\left(\nabla^{r} u^{s}-\nabla^{s} u^{r}\right)\left(\nabla_{r} u_{s}-\nabla_{s} u_{r}\right)+\left(\nabla^{r} u_{r}\right)^{2}
$$

As an almost-Hermitian manifold is an orientable Riemannian one, the theorem is applicable to our $K$-space $M$. If we put $\bar{v}_{i}=u_{i}$, then, by virtue of (2. 10), we get the following

LEMMA 2. 3. In a compact $K$-space $M$, the integral formula

$$
\begin{equation*}
\int_{M}\left[\left\{\nabla^{r} \nabla_{r} v_{i}-R_{r i} v^{r}+2 N(v)_{i}-\left(R_{r i}-R_{r i}^{*}\right) v^{r}\right\} v^{i}+S(\bar{v})\right] d \sigma=0 \tag{2.11}
\end{equation*}
$$

is valid for any vector field $v$.
3. Contravariant almost-analytic vectors. Consider an analytic vector $v$, then it holds that

$$
\begin{equation*}
\underset{v}{£} \varphi_{j}^{i} \equiv \boldsymbol{v}^{r} \nabla_{r} \varphi_{j}^{i}-\boldsymbol{\varphi}_{j}^{r} \nabla_{r} v^{i}+\varphi_{r}^{i} \nabla_{j} v^{r}=0, \tag{3.1}
\end{equation*}
$$

which is equivalent to the following equation

$$
\begin{equation*}
\boldsymbol{v}^{r} \nabla_{r} \varphi_{j t}-\varphi_{j}^{r} \nabla_{r} v_{i}-\varphi_{i}^{r} \nabla_{j} v_{r}=0 \tag{3.2}
\end{equation*}
$$

Operating $\nabla^{j}=g^{j p} \nabla_{p}$ to (3. 2), we have

[^2]$$
\left(\nabla^{j} v^{r}\right) \nabla_{r} \varphi_{j i}+v^{r} \nabla^{j} \nabla_{r} \varphi_{j i}-\varphi_{j}^{r} \nabla^{j} \nabla_{r} v_{i}-\left(\nabla^{j} \varphi_{i}^{r}\right) \nabla_{j} v_{r}-\varphi_{i}^{r} \nabla^{j} \nabla_{j} v_{r}=0 .
$$

On taking account of (1.1), (1.4) and

$$
\varphi^{j r} \nabla_{j} \nabla_{r} v_{i}=-\frac{1}{2} \varphi^{p q} R_{p q i}^{r} v_{r},
$$

we find that the equation

$$
\begin{equation*}
\nabla^{r} \nabla_{r} v_{i}+R_{r i} v^{r}=0 \tag{3.3}
\end{equation*}
$$

holds good for an analytic vector $v$. Hence we have
THEOREM 3. 1. In a compact $K$-space, if an analytic vector $v$ satisfies $\nabla^{r} v_{r}=0$, then it is a Killing vector.

In an $n$-dimensional Riemannian manfold $V_{n}$, if a vector field $v$ satisfies

$$
\begin{equation*}
\underset{v}{£} g_{j i} \equiv \nabla_{j} v_{i}+\nabla_{i} v_{j}=2 \phi g_{j i}, \tag{3.4}
\end{equation*}
$$

where $\phi$ is a scalar function, then it is called a conformal Killing vector. A conformal Killing vector $v$ satisfies

$$
\begin{equation*}
\nabla^{r} \nabla_{r} v_{i}+R_{r i} v^{r}+\frac{n-2}{n} \nabla_{i} \nabla_{r} v^{r}=0,{ }^{13)} \tag{3.5}
\end{equation*}
$$

by virtue of the Ricci's identity and (3.4).
Now we suppose that $n>2$ and $M$ is compact. If a conformal Killing vector $v$ is at the same time analytic, then we have from (3.3) and (3. 5)

$$
\nabla_{i} \nabla_{r} v^{r}=0,
$$

from which it follows that $\nabla_{r} v^{r}=$ const.. As $M$ is compact, $\nabla_{r} v^{r}=0$ by virtue of the Green's theorem. Hence, we have the following

THEOREM 3. 2. If an n-dimensional $K$-space $(n>2)$ is compact, a conformal Killing vector which is at the same time analytic is a Killing vector.

In $V_{n}$, a vector field $v$ which satisfies the equation

$$
\underset{v}{£}\left\{\begin{array}{l}
h i \tag{3.6}
\end{array}\right\} \equiv \nabla_{j} \nabla_{i} v^{h}+R_{r j i}{ }^{h} v^{r}=\delta_{j}{ }^{h} \psi_{i}+\delta_{i}{ }^{h} \psi_{j},
$$

where $\psi_{i}$ is a certain vector, is called a projective Killing vector. For a projective Killing vector $v$, we have

$$
\nabla^{r} \nabla_{r} v_{i}+R_{r i} v^{r}=\frac{2}{n+1} \nabla_{i} \nabla_{r} v^{r},
$$

from which we can obtain the following
ThEOREM 3. 3. In a compact $K$-space, if a projective Killing vector
13) Cf. K. Yano [7].
is at the same time analytic, then it is a Killing vector.
By an analogous method ${ }^{14)}$ as in almost-Kählerian manifold, we have easily the following

ThEOREM. 3. 4. In a compact $K$-space, the integral

$$
\int_{M}\left(R_{r i} v^{r} v^{i}\right) d \sigma
$$

is positive or zero for any analytic vector $v$.
Corollary. If a compact $K$-space is an Einstein space with $R<0$, then there does not exist a non-trivial analytic vector.

In a compact almost-Kählerian manifold, the equation (3.3) is a sufficient condition in order that $v$ is an analytic vector. But in a $K$-space, the equation (3.3) is not sufficient. In the next place we shall obtain another equation which must be satisfied by an analytic vector.

If we operate $\phi^{k j} \nabla_{k}$ to (3.2) then we get

$$
\varphi^{k j} \nabla_{k}\left(v^{r} \nabla_{r} \varphi_{j i}-\varphi_{j}^{r} \nabla_{r} v_{i}-\varphi_{i}^{r} \nabla_{j} v_{r}\right)=0 .
$$

The left hand side is the sum of the following six terms $a_{1}, \ldots \ldots, a_{6}$.

$$
\begin{aligned}
& a_{1}=\phi^{k j}\left(\nabla_{k} v^{r}\right) \nabla_{r} \varphi_{j i}=-\left(\nabla^{k} v^{r}\right)\left(\nabla_{j} \boldsymbol{\varphi}_{k r}\right) \boldsymbol{\varphi}_{i}{ }^{j}=-N(v)_{i}, \\
& a_{2}=\phi^{k j} v^{r} \nabla_{k} \nabla_{r} \varphi_{j i}=0 .
\end{aligned}
$$

The validity of the last equality owes to (1.1), the Ricci's identity and (2. 4).

$$
\begin{aligned}
& a_{3}=-\phi^{k j}\left(\nabla_{k} \varphi_{j}^{r}\right) \nabla_{r} v_{i}=0, \\
& a_{4}=-\phi^{k j} \boldsymbol{\varphi}_{j}^{r} \nabla_{k} \nabla_{r} v_{i}=\nabla^{r} \nabla_{r} v_{i}, \\
& a_{5}=-\phi^{k j}\left(\nabla_{k} \varphi_{i}^{r}\right) \nabla_{j} v_{r}=-N(v)_{i}, \\
& a_{6}=-\phi^{k j} \boldsymbol{\varphi}_{i}^{r} \nabla_{k} \nabla_{j} v_{r}=R_{r i}^{*} v^{r} .
\end{aligned}
$$

Hence we have

$$
\begin{equation*}
\nabla^{r} \nabla_{r} v_{i}+R_{r i}^{*} v^{r}-2 N(v)_{i}=0 \tag{3.7}
\end{equation*}
$$

for an analytic vector $v$. From (3.3) and (3.7), we get the following equation

$$
\begin{equation*}
\left(R_{r i}-R_{r i}^{*}\right) v^{r}=-2 N(v)_{i} . \tag{3.8}
\end{equation*}
$$

We shall see in $\S 5$ that, in a compact $K$-space, (3.3) and (3.8) constitute a set of sufficient conditions in order that $v$ is an analytic vector.
4. Covariant almost-analytic vectors. In § 1 , a covariant analytic vector field was defined. In the present section we shall obtain equations which must be satisfied by such vectors.

[^3]For covariant analytic vector $v$, we have

$$
\left(\nabla_{j} \varphi_{i}^{r}-\nabla_{i} \varphi_{j}^{r}\right) v_{r}=\varphi_{j}{ }^{r} \nabla_{r} v_{i}-\varphi_{i}^{r} \nabla_{j} v_{r} .
$$

On account of (1.1), the last equation is equivalent to

$$
\begin{equation*}
2 v^{r} \nabla_{r} \boldsymbol{\varphi}_{j i}-\boldsymbol{\varphi}_{j}{ }^{r} \nabla_{r} v_{i}+\boldsymbol{\varphi}_{i}{ }^{r} \nabla_{j} v_{r}=0 . \tag{4.1}
\end{equation*}
$$

As an analytic vector $v$ is defined by (3.2)i. e.

$$
v^{r} \nabla_{r} \varphi_{j i}-\varphi_{j}^{r} \nabla_{r} v_{i}-\varphi_{i}^{r} \nabla_{j} v_{r}=0,
$$

if we notice the similarity of (4.1) and the last equation, then we shall be able to avoid some complication in the following calculation.

If we operate $\nabla^{j}$ to (4.1), it follows that

$$
2\left(\nabla^{j} v^{r}\right) \nabla_{r} \varphi_{j i}+2 v^{r} \nabla^{j} \nabla_{r} \varphi_{j \imath}-\varphi_{j}^{r} \nabla^{j} \nabla_{r} v_{i}+\left(\nabla^{j} \phi_{i}^{r}\right) \nabla_{j} v_{r}+\varphi_{i}^{r} \nabla^{j} \nabla_{j} v_{r}=0 .
$$

Hence, ky virtue of (1. 1) and (1. 4), we obtain

$$
\begin{equation*}
\nabla^{r} \nabla_{r} v_{i}+R_{r i}^{*} v^{r}-2 R_{r i} v^{r}+3 N(v)_{i}=0 . \tag{4.2}
\end{equation*}
$$

Next we operate $\boldsymbol{\varphi}^{k j} \nabla_{k}$ to (4.1) and obtain the equation

$$
\boldsymbol{\varphi}^{k j} \nabla_{k}\left(2 v^{r} \nabla_{r} \varphi_{j i}-\varphi_{j}^{r} \nabla_{r} v_{i}+{\varphi_{i}}^{r} \nabla_{j} v_{r}\right)=0 .
$$

The left hand member is the sum of the following six terms $a_{1}, \ldots \ldots, a_{0}$. Making use of the notation in §3, we have

$$
\begin{array}{lll}
a_{1}^{\prime}=2 a_{1}, & a_{2}^{\prime}=2 a_{2}, & a_{3}^{\prime}=a_{3}, \\
a_{4}^{\prime}=a_{4}, & a_{5}^{\prime}=-a_{5}, & a_{6}^{\prime}=-a_{6} .
\end{array}
$$

Therefore we get

$$
\begin{equation*}
\nabla^{r} \nabla_{r} v_{i}-R_{r i}^{*} v^{r}-N(v)_{i}=0 . \tag{4.3}
\end{equation*}
$$

From (4. 2) and (4. 3), it follows that the equation

$$
\begin{equation*}
\left(R_{r i}-R_{r i}^{*}\right) v^{r}=2 N(v)_{i} \tag{4.4}
\end{equation*}
$$

holds good. Substituting (4.4) in (4. 2), we obtain

$$
\begin{equation*}
\nabla^{r} \nabla_{r} v_{i}-R_{r i} v^{r}+N(v)_{i}=0 \tag{4.2}
\end{equation*}
$$

for a covariant analytic vector $v$.
5. The integral formula. In this section we shall $o^{\prime}$ tain a integral formula concerning a vector field in a compact $K$-space and prove a theorem which gives a necessary and sufficient condition for an analytic vector.

Let $v$ be a vector field and introduce a tensor $a(v)_{j k}$ by

$$
\begin{align*}
a(v)_{j k} & =\left(\underset{v}{£} \boldsymbol{\varphi}_{j}^{l}\right) \boldsymbol{\varphi}_{l k}  \tag{5,1}\\
& =v^{r}\left(\nabla_{r} \boldsymbol{\varphi}_{j}^{l}\right) \boldsymbol{\varphi}_{l k}-\boldsymbol{\varphi}_{j}^{r}\left(\nabla_{r} v^{l}\right) \boldsymbol{\varphi}_{l k}-\nabla_{j} v_{k} .
\end{align*}
$$

For simplicity, we shall denote $a_{j \mathrm{k}}$ instead of $a(v)_{j k}$ in the following. $a_{j k}=$ 0 is equivalent to the fact that the vector $v$ is an analytic vector.

In the first place we shall compute $\nabla^{j} a_{j k}$, which is the sum of the fol-
lowing six terms $A_{1}, \ldots \ldots, \mathrm{~A}_{6}$.

$$
\begin{aligned}
& A_{1}=\left(\nabla^{j} v^{r}\right)\left(\nabla_{r} \boldsymbol{\varphi}_{j}^{l}\right) \boldsymbol{\varphi}_{l k}=N(v)_{k}, \\
& A_{2}=v^{r}\left(\nabla^{j} \nabla_{r} \boldsymbol{\varphi}_{j}^{l}\right) \boldsymbol{\varphi}_{l k}=\left(R_{r k}^{*}-R_{r k}\right) v^{r}, \\
& A_{3}=v^{r}\left(\nabla_{r} \boldsymbol{\varphi}_{j}^{l}\right) \nabla^{j} \boldsymbol{\varphi}_{l k}=\left(R_{r k}-R_{r k}^{*}\right) v^{r}, \\
& A_{4}=-\boldsymbol{\varphi}_{j}^{r}\left(\nabla^{j} \nabla_{r} v^{l}\right) \boldsymbol{\varphi}_{l k}=-R_{r k}^{*} v^{r}, \\
& A_{5}=-\boldsymbol{\varphi}_{j}^{r}\left(\nabla_{r} v^{l}\right) \nabla^{j} \boldsymbol{\varphi}_{l k}=N(v)_{k}, \\
& A_{6}=-\nabla^{j} \nabla_{j} v_{k} .
\end{aligned}
$$

Then we get

$$
\begin{equation*}
\nabla^{j} a_{j k}=-\left(\nabla^{j} \nabla_{j} v_{k}+R_{r k}^{*} v^{r}\right)+2 N(v)_{k} . \tag{5.2}
\end{equation*}
$$

In the next place we shall compute

$$
\nabla^{j}\left(a_{j k} v^{k}\right)=v^{k} \nabla^{j} a_{j k}+a_{j k} \nabla^{j} v^{k} .
$$

If we substitute (5. 1) and (5.2) in the last equation, we have after some calculation,

$$
\begin{align*}
\nabla^{j}\left(a_{j k} v^{k}\right)= & -\left(\nabla^{j} \nabla_{j} v_{k}+R_{r k}^{*} v^{r}\right)+N(v)_{k} v^{k}  \tag{5.3}\\
& +\boldsymbol{\phi}^{j r} \boldsymbol{\phi}^{k l}\left(\nabla_{j} v_{k}\right) \nabla_{r} v_{l}-\left(\nabla_{j} v_{k}\right) \nabla^{j} v^{k} .
\end{align*}
$$

Now if we put $a^{2}(v)=a_{j k} a^{j k}$, then

$$
\begin{aligned}
a^{2}(v) & =\left[v^{r}\left(\nabla_{r} \boldsymbol{\varphi}_{j}{ }^{l}\right) \boldsymbol{\varphi}_{l k}-\boldsymbol{\varphi}_{j}{ }^{r}\left(\nabla_{r} v^{l}\right) \boldsymbol{\varphi}_{l k}-\nabla_{j} v_{k}\right] \\
& \times\left[v^{p}\left(\nabla_{p} \boldsymbol{\varphi}^{j s}\right) \boldsymbol{\varphi}_{s}{ }^{k}-\boldsymbol{\varphi}^{j p}\left(\nabla_{p} v^{s}\right) \boldsymbol{\varphi}_{s}{ }^{k}-\nabla^{j} v^{k}\right]
\end{aligned}
$$

is the sum of the following nine terms $B_{1}, \ldots, B_{9}$.

$$
\begin{array}{ll}
B_{1}=v^{r}\left(\nabla_{r} \boldsymbol{\varphi}_{j}^{l}\right) \boldsymbol{\varphi}_{l k} v^{p}\left(\nabla_{p} \boldsymbol{\varphi}^{j s}\right) \boldsymbol{\varphi}_{s}^{k} & =\left(R_{r p}-R_{r p}^{*}\right) v^{r} v^{p}, \\
B_{2}=-v^{r}\left(\nabla_{r} \boldsymbol{\varphi}_{j}\right) \boldsymbol{\varphi}_{l k} \boldsymbol{\varphi}^{j p}\left(\nabla_{p} v^{s}\right) \boldsymbol{\varphi}_{s}^{k} & =N(v)_{r} v^{r}, \\
B_{3}=-v^{r}\left(\nabla_{r} \boldsymbol{\varphi}_{j}^{l}\right) \boldsymbol{\varphi}_{l k} \nabla^{j} v^{k} & =B_{2}, \\
B_{4}=-\boldsymbol{\varphi}_{j}{ }^{r}\left(\nabla_{r} v^{l}\right) \boldsymbol{\varphi}_{l l} v^{p}\left(\nabla_{p} \boldsymbol{\varphi}^{j s}\right) \boldsymbol{\varphi}_{s}^{k} & =B_{2}, \\
B_{5}=\boldsymbol{\varphi}_{j}^{r}\left(\nabla_{r} v^{v}\right) \boldsymbol{\varphi}_{l k} \boldsymbol{\varphi}^{j p}\left(\nabla_{p} \boldsymbol{v}^{s}\right) \boldsymbol{\varphi}_{s}{ }^{k} & =\left(\nabla_{p} v_{l}\right) \nabla^{p} v^{l}, \\
B_{6}=\boldsymbol{\varphi}_{j}^{r}\left(\nabla_{r} v^{l}\right) \boldsymbol{\varphi}_{l k} \nabla^{j} v^{k} & =-\boldsymbol{\varphi}^{j r} \boldsymbol{\varphi}^{k l}\left(\nabla_{j} v_{k}\right) \nabla_{r} v_{l}, \\
B_{7}=-\left(\nabla_{j} v_{k}\right) v^{p}\left(\nabla_{p} \boldsymbol{\varphi}^{j s}\right) \boldsymbol{\varphi}_{s}{ }^{k} & =B_{2}, \\
B_{8}=\nabla_{j} v_{k} \boldsymbol{\varphi}^{j p}\left(\nabla_{p} v^{s}\right) \boldsymbol{\varphi}_{s}{ }^{k}=B_{6}, & \\
B_{9}=\left(\nabla^{j} v^{k}\right) \nabla_{j} v_{k}=B_{5} . &
\end{array}
$$

Therefore we get

$$
\begin{align*}
a^{2}(v)=\left(R_{r p}\right. & \left.-R_{r p}^{*}\right) v^{r} v^{p}+4 N(v)_{r} v^{r}-2 \phi^{j r} \boldsymbol{\varphi}^{k l}\left(\nabla_{j} v_{k}\right) \nabla_{r} v_{l}  \tag{5.4}\\
& +2\left(\nabla_{j} v_{k}\right) \nabla^{j} v^{k} .
\end{align*}
$$

Consequently, from (5.3) and (5.4), we have

$$
\nabla^{j}\left(a_{j k} v^{k}\right)+\frac{1}{2} a^{2}(v)=-\left(\nabla^{j} \nabla_{j} v_{k}+R_{r k} v^{r}\right) v^{k}
$$

$$
+\frac{3}{2}\left\{2 N(v)_{k}+\left(R_{r k}-R_{r k}^{*}\right) v^{r}\right\} v^{k} .
$$

If $M$ is compact, by integration of the last equation, we have the following

THEOREM 5. 1. In a compact $K$-space $M$, the integral formula

$$
\begin{align*}
\int_{M}\left[\left(\nabla^{j} \nabla_{j} v_{k}\right.\right. & \left.\left.+R_{r k} v^{r}\right) v^{k}+\frac{1}{2} a^{2}(v)\right] d \sigma \\
& =\frac{3}{2} \int_{M}\left[2 N(v)_{k}+\left(R_{r k}-R_{r k}^{*}\right) v^{r}\right] v^{k} d \sigma \tag{5.5}
\end{align*}
$$

is valid for any vector field $v$, where

$$
\begin{gathered}
a^{2}(v)=a_{j k} a^{j k}, a_{j k}=\left(\underset{v}{£} \varphi_{j}^{l}\right) \boldsymbol{\varphi}_{l k}, \\
N(v)_{i}=\frac{1}{4}\left(\nabla^{p} v^{q}\right) N_{p q i}
\end{gathered}
$$

and $N_{p a i}, R_{r i}^{*}$ are given by (2.7) and (1.3) respectively.
In §3 we have seen that an analytic vector $v$ satisfies the following equations

$$
\begin{gather*}
\nabla^{r} \nabla_{r} v_{i}+R_{r i} v^{r}=0,  \tag{5.6}\\
2 N(v)_{i}+\left(R_{r i}-R_{r i}^{*}\right) v^{r}=0 .
\end{gather*}
$$

Now consider a vector field $v$ satisfying (5.6) and (5.7). Then if $M$ is compact, we have $a^{2}(v)=0$ i. e. $a_{j k}=0$ by virtue of (5.5), so $v$ is analytic. Thus we have the

THEOREM 5. 2. In a compact $K$-space $M$, a necessary and sufficient condition in order that a vector $v$ be analytic is that equations (5. 6) and (5. 7) are both satisfied.
6. Another integral formula. Consider a vector field $v$ and put

$$
\begin{aligned}
b(v)_{j k} & =\left(2 v^{r} \nabla_{r} \varphi_{j}^{l}-\boldsymbol{\varphi}_{j}^{r} \nabla_{r} v^{l}-\boldsymbol{\varphi}_{r}^{l} \nabla_{j} v^{r}\right) \boldsymbol{\varphi}_{l k} \\
& =2 v^{r}\left(\nabla_{r} \boldsymbol{\varphi}_{j}^{l}\right) \boldsymbol{\varphi}_{l k}-\boldsymbol{\varphi}_{j}^{r}\left(\nabla_{r} v^{l}\right) \boldsymbol{\varphi}_{l k}+\nabla_{j} v_{k} .
\end{aligned}
$$

$b(v)_{j k}=0$ is equivalent to the fact that the vector $v$ is covariant analytic. For simplicity we write $b_{j k}$ instead of $b(v)_{j k}$. Using the notation in §5, $\nabla^{3} b_{j k}$ is the sum of the following six terms $A_{1}{ }^{\prime}, \ldots \ldots, A_{6}{ }^{\prime}$.

$$
\begin{array}{lll}
A_{1}^{\prime}=2 A_{1}, & A_{2}^{\prime}=2 A_{2}, & A_{3}^{\prime}=2 A_{3} \\
A_{4}^{\prime}=A_{4}, & A_{5}^{\prime}=A_{5}, & A_{6}^{\prime}=-A_{6}
\end{array}
$$

Hence we have

$$
\nabla^{j} b_{j k}=\nabla^{j} \nabla_{j} v_{k}-R_{r k}^{*} v^{r}+3 N(v)_{k} .
$$

After some calculation we get
(6. 1)

$$
\begin{aligned}
\nabla^{j}\left(b_{j k} v^{k}\right) & =\left(\nabla^{j} \nabla_{j} v_{k}-R_{r k}^{*} v^{r}\right) v^{k}+N(v)_{k} v^{k} \\
& +\varphi^{j r} \boldsymbol{\varphi}^{k l}\left(\nabla_{j} v_{k}\right) \nabla_{r} v_{l}+\left(\nabla_{j} v_{k}\right) \nabla^{j} v^{k}
\end{aligned}
$$

If we put $b^{2}(v)=b_{j k} b^{j k}$, then it is the sum of the following nine terms $B_{1}, \ldots$ $\ldots, B_{9}{ }^{\prime}$.

$$
\begin{array}{lll}
B_{1}^{\prime}=4 B_{1}, & B_{2}^{\prime}=2 B_{2}, & B_{3}^{\prime}=-2 B_{3}, \\
B_{4}^{\prime}=2 B_{4}, & B_{5}^{\prime}=B_{5}, & B_{6}^{\prime}=-B_{6}, \\
\mathrm{~B}_{7}^{\prime}=-2 B_{7}, & B_{8}^{\prime}=-B_{8}, & B_{9}^{\prime}=B_{9} .
\end{array}
$$

Hence we have

$$
\begin{align*}
b^{2}(v)=4\left(R_{r k}\right. & \left.-R_{r k}^{*}\right) v^{r} v^{k}+2\left(\nabla_{j} v_{k}\right) \nabla^{j} v^{k}  \tag{6.2}\\
& +2 \boldsymbol{\phi}^{j r} \boldsymbol{\phi}^{k l}\left(\nabla_{j} v_{k}\right) \nabla_{r} v_{l} .
\end{align*}
$$

Therefore, from (6.1) and (6.2), we get

$$
\begin{aligned}
\nabla^{j}\left(b_{j k} v^{k}\right) & -\frac{1}{2} b^{2}(v)=\left(\nabla^{j} \nabla_{j} v_{k}-R_{r k} v^{r}\right) v^{k} \\
& +\left\{N(v)_{k}-\left(R_{r k}-R_{r k}^{*}\right) v^{r}\right\} v^{k}
\end{aligned}
$$

Thus we have the following
LEmma 6. 1 . In a compact $K$-space $M$, the integral formula

$$
\begin{equation*}
\int_{M}\left[\left\{\nabla^{j} \nabla_{j} v_{i}-R_{r i} v^{r}+N(v)_{i}-\left(R_{r i}-R_{r i}^{*}\right) v^{\cdot}\right\} v^{i}+\frac{1}{2} b^{2}(v)\right] d \sigma=0 \tag{6.3}
\end{equation*}
$$ is valid for any vector field $v$.

On the other hand, in compact $M$, we have Lemma 2.3. If we subtract (6. 3) from the twice of (2.11), it follows the following

THEOREM 6. 2. In a compact $K$-space $M$, the integral formula

$$
\begin{aligned}
\int_{M}\left[\left(\nabla^{r} \nabla_{r} v_{i}\right.\right. & \left.\left.-R_{r i} v^{r}+N(v)_{i}\right)+\left\{2 N(v)_{i}-\left(R_{r i}-R_{r i}^{*}\right) v^{r}\right\}\right] v^{i} d \sigma \\
& =\int_{M}\left[\begin{array}{l}
1 \\
2
\end{array} b^{2}(v)-2 S(\widetilde{v})\right] d \sigma
\end{aligned}
$$

is valid for any vector field $v$.
In §4 we have seen that a covariant analytic vector $v$ satisfies the following equations

$$
\begin{equation*}
\nabla^{r} \nabla_{r} v_{i}-R_{r i} v^{r}+N(v)_{i}=0 \tag{6.4}
\end{equation*}
$$

$2 N(v)_{i}-\left(R_{r i}-R_{r i}^{*}\right) v^{r}=0$.
Now, let $v$ be a covariant analytic vector, then (6.4), (6.5) and $b^{2}(v)=0$ hold good. Hence, in compact $M, S(\widetilde{v})=0$, y virtue of Theorem 6. 2. Thus, from the definition of $S(\widetilde{v})$, the vector $\widetilde{v}$ is harmonic. As $\bar{v}$ is also a cova-
riant analytic vector, $v$ is also harmonic by the same argument. Conversely, let $v$ and $\bar{v}$ be both harmonic, then their components satisfy (1.9) trivially, so $v$ is a covariant analytic vector. Thus we have

THEOREM 6. 3. In a compact $K$-space $M$, a necessary and sufficient condition in order that a vector $v$ be covariant analytic is that $v$ and $\bar{v}$ are both harmonic.

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[^0]:    1) This paper was prepared in a term when the present author was ordered to study at
[^1]:    8) S. Tachibana [5].
    9) In (1.9), $\nabla$ may be replaced by $\partial$.
[^2]:    12) For example, K. Yano [7].
[^3]:    14) S. Tachibana [5].
