THE OPERATING CHARACTERISTIC OF THE CONTROL CHART FOR SAMPLE MEANS¹

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- 1. Summary. In this paper we derive the operating characteristic of the control chart for sample means when process standards are unspecified. Under the null hypothesis the distribution of the process is $N(\mu, \sigma^2)$, where μ and σ are fixed but unknown. Under the alternative the process mean is a random variable with a $N(\mu, \theta^2 \sigma^2)$ distribution. Exact results are obtained for cases ranging from two samples of size 2 to four samples of 10. Bounds on the operating characteristic are obtained in particular cases ranging from five samples of 5 to 25 samples of 10.
- 2. Introduction. The usual procedure in constructing control charts from past data consists of the following steps [1].
- (a) Classify the total number, N say, of observations to be drawn from the process into m samples of size n according to some rational method of subgrouping.
- (b) For each sample, calculate a mean and a range, plotting these values on separate charts in the order drawn.
- (c) Using prescribed formulae based on the data collected and the sample size, calculate upper and lower control limits for each chart.
- (d) If all the plotted points fall within the control limits on both charts, accept the hypothesis that the process is in a state of statistical control. Otherwise, reject this hypothesis.

In what follows we shall confine our attention to the control chart for means. Letting x_{ij} denote the jth observation in the ith random sample of size n, we will be concerned with the following linear model

$$x_{ij} = \mu_i + \epsilon_{ij},$$
 $i = 1, 2, \dots, m; j = 1, 2, \dots, n,$

where

- (1) the ϵ_{ij} are statistically independent and distributed according to $N(0, \sigma^2)$;
- (2) the μ_i are statistically independent and distributed according to $N(\mu, \theta^2 \sigma^2)$;
- (3) the μ_i are statistically independent of the ϵ_{ij} ;
- (4) μ and σ are fixed but unknown.

Let \bar{x}_i and r_i denote the mean and range, respectively, of the *i*th sample x_{i1}, \dots, x_{in} . The usual control chart procedure prescribes that the limits on the \bar{x} -chart be set at $\bar{x} \pm A_2\bar{r}$, where

$$\bar{x} = \frac{1}{mn} \sum_{j=1}^{n} \sum_{i=1}^{m} x_{ij}, \quad \bar{r} = \frac{1}{m} \sum_{i=1}^{m} r_{i},$$

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and A_2 is defined by $E(A_2\bar{r}) = 3\sigma/\sqrt{n}$ when the underlying distribution is normal. What we seek then is the probability that the inequalities

$$\bar{x} - A_2 \bar{r} < \bar{x}_i < \bar{x} + A_2 \bar{r}, \qquad i = 1, 2, \cdots, m,$$

be satisfied simultaneously. Defining

$$(2.1) \quad \beta(k) = P\left(-\frac{k}{3}A_2\bar{r} < \bar{x}_1 - \bar{x} < \frac{k}{3}A_2\bar{r}, \cdots, -\frac{k}{3}A_2\bar{r} < \bar{x}_m - \bar{x} < \frac{k}{3}A_2\bar{r}\right)$$

we wish to evaluate $\beta(3)$ under the hypotheses

$$H_0:\theta=0;$$

$$H_1: \theta > 0.$$

The null hypothesis, H_0 , is the hypothesis of statistical control. Our choice of the alternative $\theta > 0$ is motivated by practical considerations. Since shifts in the mean of an industrial process might occur at any time and be of any magnitude, an alternative which ordered the μ_i in a particular way would be of limited interest. By treating the μ_i as random variables we are taking into account the "average effect" of m independent assignable causes of varying magnitude. Although we are unable to specify the size of any particular shift, a measure of the size of the μ_i as a group is given by the parameter θ .

3. Taylor's series expansion of $\beta(3)$. The general method employed in calculating $\beta(3)$ is first to obtain

$$(3.1) \beta_{0}(k) = P\left(-k\frac{\sigma}{\sqrt{n}} < \bar{x}_{1} - \bar{x} < k\frac{\sigma}{\sqrt{n}}, \cdots, -k\frac{\sigma}{\sqrt{n}} < \bar{x}_{m} - \bar{x} < k\frac{\sigma}{\sqrt{n}}\right)$$

$$= P\left(-k < \frac{\bar{x}_{1} - \bar{x}}{\sigma/\sqrt{n}} < k, \cdots, -k < \frac{\bar{x}_{m} - \bar{x}}{\sigma/\sqrt{n}} < k\right)$$

as a function of k for fixed m. We note that $\beta_0(k)$ is of considerable interest in its own right, since $\beta_0(3)$ represents the probability that the \bar{x} -chart will show control when σ is known.

To evaluate $\beta(3)$ we multiply the conditional probability that (for fixed \bar{r}) $-A_2\bar{r} < \bar{x}_i - \bar{x} < A_2\bar{r}$ $(i = 1, 2, \dots, m)$ by the pdf of \bar{r} and integrate on \bar{r} from 0 to ∞ . For fixed \bar{r} we have

$$P(-A_2\bar{r}<\bar{x}_1-\bar{x}< A_2\bar{r},\cdots)$$

$$= P\left(-\frac{A_2\bar{r}}{\sigma/\sqrt{n}} < \frac{\bar{x}_1 - \bar{x}}{\sigma/\sqrt{n}} < \frac{A_2\bar{r}}{\sigma/\sqrt{n}}, \cdots\right) = \beta_0\left(\frac{\sqrt{n} A_2\bar{r}}{\sigma}\right).$$

Let $g_{mn}(\bar{r}; \sigma)$ denote the pdf of the average range of m random samples of n from a $N(\mu, \sigma^2)$ universe. Then

$$\beta(3) = \int_0^\infty g_{mn}(w; \sigma) \beta_0 \left(\sqrt{n} A_2 \frac{w}{\sigma} \right) dw.$$

Letting $g_{mn}(w; 1) = g_{mn}(w)$, we have

$$g_{mn}(w; \sigma) = \frac{1}{\sigma} g_{mn} \left(\frac{w}{\sigma} \right).$$

Thus

$$\beta(3) = \int_0^\infty \frac{1}{\sigma} g_{mn} \left(\frac{w}{\sigma} \right) \beta_0 \left(\sqrt{n} A_2 \frac{w}{\sigma} \right) dw.$$

Finally, letting $\bar{r} = w/\sigma$ yields

(3.2)
$$\beta(3) = \int_0^\infty g_{mn}(\bar{r})\beta_0(\sqrt{n}A_2\,\bar{r})\,d\bar{r}.$$

We now expand $\beta_0(\sqrt{n} \ A_2\bar{r})$ in a Taylor's series with remainder about the point $\bar{r} = d_2$, where $d_2\sigma$ denotes the expected value of the range in a random sample of n from a $N(\mu, \sigma^2)$ population. Clearly

$$(3.3) \quad \beta_0(\sqrt{n}A_2\bar{r}) = \beta_0(3) + b_1(\bar{r} - d_2) + \cdots + \frac{b_p}{p!}(\bar{r} - d_2)^p + R'(\xi),$$

where the b_i are the *i*th derivatives of $\beta_0(\sqrt{n} \ A_2\bar{r})$ with respect to \bar{r} , evaluated at $\bar{r} = d_2$, and

$$(3.4) R'(\xi) = \frac{b_{p+1}(\xi)}{(p+1)!} (\bar{r} - d_2)^{p+1}, \xi = d_2 + \alpha(\bar{r} - d_2), 0 \le \alpha \le 1.$$

This expansion is valid since all the b_i are continuous. Now, taking the expectation of both sides of (3.3) yields

$$\int_{0}^{\infty} g_{mn}(\bar{r})\beta_{0}(\sqrt{n}A_{2}\bar{r}) d\bar{r} = \beta_{0}(3) \int_{0}^{\infty} g_{mn}(\bar{r}) d\bar{r} + b_{1} \int_{0}^{\infty} (\bar{r} - d_{2})g_{mn}(\bar{r}) d\bar{r} + \cdots + \int_{0}^{\infty} R'(\xi)g_{mn}(\bar{r}) d\bar{r}$$

But since the first integral on the right side is unity and the second zero, we have

(3.5)
$$\beta(3) = \beta_0(3) + \frac{b_2}{2!} \mu_2(\bar{r}) + \cdots + \frac{b_p}{p!} \mu_p(\bar{r}) + R,$$

where the $\mu_i(\bar{r})$ are central moments of average range, and

(3.6)
$$R = \int_0^\infty \frac{b_{p+1}(\xi)}{(p+1)!} (\bar{r} - d_2)^{p+1} g_{mn}(\bar{r}) d\bar{r}.$$

For the actual numerical computation of $\beta(3)$, relation (3.5) is used in the form

$$(3.7) \quad \beta(3) = \beta_0(3) + \frac{b_2}{2!} \frac{\mu_2(r)}{m} + \frac{b_3}{3!} \frac{\mu_3(r)}{m^2} + \frac{b_4}{4!} \frac{1}{m^3} \left[\mu_4(r) + 3(m-1)\mu_2^2(r) \right] + \cdots,$$

where the $\mu_i(r)$ are the *i*th central moments of the range in samples of n from a $N(\mu, 1)$ population. In each case, a sufficient number of terms of (3.7) is used to insure that the remainder, R, is small.

4. Derivation of $g_0(\mathbf{k})$. As indicated in the previous section, our first task is to obtain an expression for $\beta_0(k)$. It is apparent that it can be written as

$$\beta_0(k) = P\left(\frac{\bar{x}_{(m)} - \bar{x}}{\sigma/\sqrt[4]{n}} < k, \frac{\bar{x} - \bar{x}_{(1)}}{\sigma/\sqrt{n}} < k\right),$$

where $\bar{x}_{(m)}$ and $\bar{x}_{(1)}$ are the largest and smallest sample means, respectively. To obtain a tractable expression for this probability we shall first investigate the joint distribution of $\frac{\bar{x}_{(m)} - \bar{x}}{\sigma/\sqrt{n}}$ and $\frac{\bar{x} - \bar{x}_{(1)}}{\sigma/\sqrt{n}}$. For this purpose let us consider the joint pdf of the ordered variates $\bar{x}_{(1)} < \bar{x}_{(2)} < \cdots < \bar{x}_{(m)}$. Since $\bar{x}_i = \mu_i + \bar{\epsilon}_i$, where $\bar{\epsilon}_i = \sum_{j=1}^n \epsilon_{ij}/n$, we see that the distribution of \bar{x}_i is normal with mean μ and variance $(\theta^2 + 1/n)\sigma^2$. Assuming $\mu = 0$ (with no loss of generality) we have

$$f(\bar{x}_{(1)}, \dots, \bar{x}_{(m)}) = \frac{m!}{(2\pi)^{m/2} \left(\frac{1+n\theta^2}{n}\right)^{m/2} \sigma^m} \exp\left[-\frac{n}{2(1+n\theta^2)\sigma^2} \sum_{i=1}^m \bar{x}_{(i)}^2\right]$$

as the joint pdf of $\bar{x}_{(1)} < \bar{x}_{(2)} < \cdots < \bar{x}_{(m)}$. To obtain the joint distribution of $\frac{\bar{x}_{(m)} - \bar{x}}{\sigma/\sqrt{n}}$ and $\frac{\bar{x} - \bar{x}_{(1)}}{\sigma/\sqrt{n}}$, let

$$\frac{\sigma}{\sqrt{n}} \sqrt{2} v_1 = -\bar{x}_{(2)} + \bar{x}_{(3)},$$

$$\frac{\sigma}{\sqrt{n}} \sqrt{3 \cdot 2} v_2 = -\bar{x}_{(2)} - \bar{x}_{(3)} + 2\bar{x}_{(4)},$$

$$\dots \dots \dots \dots \dots \dots \dots$$

$$\frac{\sigma}{\sqrt{n}} \sqrt{(m-3)(m-2)} v_{m-3} = -\bar{x}_{(2)} - \bar{x}_{(3)} - \cdots - \bar{x}_{(m-2)} + (m-3) \bar{x}_{(m-1)},$$

$$\frac{\sigma}{\sqrt{n}} \sqrt{(m-1)(m-2)} v_{m-2} = -(m-2)\bar{x}_{(1)} + \bar{x}_{(2)} + \cdots + \bar{x}_{(m-1)},$$

$$\frac{\sigma}{\sqrt{n}} \sqrt{m(m-1)} v_{m-1} = -\bar{x}_{(1)} - \bar{x}_{(2)} - \cdots - \bar{x}_{(m-1)} + (m-1) \bar{x}_{(m)},$$

$$\frac{\sigma}{\sqrt{n}} \sqrt{m} v_{m} = \bar{x}_{(1)} + \bar{x}_{(2)} + \cdots + \bar{x}_{(m-1)} + \bar{x}_{(m)}.$$

This transformation gives

$$g(v_1, \dots, v_m) = \frac{m!}{(2\pi)^{m/2}(1+n\theta^2)^{m/2}} \exp\left[-\frac{1}{2(1+n\theta^2)} \sum_{i=1}^m v_i^2\right]$$

as the joint pdf of the v_i , defined over the region S given by

$$S \begin{cases} v_{1} > 0, & v_{i} < \sqrt{\frac{i+2}{i}} v_{i+1}, & (i = 1, \dots, m-4), \\ \sqrt{m(m-2)} v_{m-1} > \sqrt{(m-1)(m-3)} v_{m-3} + v_{m-2}, \\ \sqrt{\frac{m-1}{m-2}} v_{m-2} > \frac{v_{1}}{\sqrt{2}} + \frac{v_{2}}{\sqrt{3\cdot 2}} + \dots + \frac{v_{m-3}}{\sqrt{(m-2)(m-3)}}. \end{cases}$$

Now, we integrate out v_m and let

$$v_{i} = u_{i},$$
 $(i = 1, \dots, m-3),$ $v_{m-2} = -\frac{u}{\sqrt{(m-1)(m-2)}} + \sqrt{\frac{m-1}{m-2}}v,$ $v_{m-1} = \sqrt{\frac{m}{m-1}}u,$

where in terms of the original variables

(4.2)
$$\begin{cases} u = \frac{\bar{x}_{(m)} - \bar{x}}{\sigma/\sqrt{n}}, \\ v = \frac{\bar{x} - \bar{x}_{(1)}}{\sigma/\sqrt{n}}. \end{cases}$$

The Jacobian of this transformation is $|J| = \sqrt{m/(m-2)}$. The joint density of $u_1, u_2, \dots, u_{m-3}, u, v$ is finally obtained as

(4.3)
$$h_{m}(u_{1}, \dots, u_{m-3}, u, v) = \frac{m! \sqrt{\frac{m}{m-2}}}{(2\pi)^{(m-1)/2}(1+n\theta^{2})^{(m-1)/2}} \cdot \exp\left[-\frac{1}{2(1+n\theta^{2})}\sum_{i=1}^{m-3}u_{i}^{2}\right] \exp\left[-\frac{\Lambda_{m}}{2(1+n\theta^{2})}\right]$$

over S', where

$$\Lambda_{m} = \frac{m-1}{m-2} (u^{2} + v^{2}) - \frac{2}{m-2} uv,$$

$$S' \text{ is } \begin{cases}
u_{1} > 0, u > 0, v > 0, u_{i} < \sqrt{\frac{i+2}{i}} u_{i+1}, & (i = 1, \dots, m-4), \\
\frac{u_{1}}{\sqrt{2}} + \frac{u_{2}}{\sqrt{3 \cdot 2}} + \dots + \frac{u_{m-3}}{\sqrt{(m-2)(m-3)}} < \frac{1}{m-2} [(m-1)v - u], \\
\sqrt{(m-2)(m-3)} u_{m-3} < (m-1)u - v.$$

For the cases m = 2 through m = 4, $\beta_0(k)$ is obtained by integrating (4.3) over the range u_1 , \dots , $u_{m-3} \varepsilon S'$, u < k, v < k. $\beta(3)$ is then evaluated from the series (3.7). For cases where m > 4, bounds on the desired probabilities are obtained by methods described in Section 5D.

5. Exact evaluation of $\beta_0(k)$ and $\beta(3)$.

A. Case m = 2. In this case, $\beta_0(k)$ becomes simply

$$\beta_0(k) = P\left(-k < \frac{\bar{x}_1 - \bar{x}_2}{2\sigma/\sqrt{n}} < k\right)$$

$$= \Phi\left(\frac{\sqrt{2}k}{\sqrt{1 + n\theta^2}}\right) - \Phi\left(-\frac{\sqrt{2}k}{\sqrt{1 + n\theta^2}}\right),$$
(5.1)

where $\Phi(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{x} e^{-\frac{1}{2}t^2} dt$. The series expansion for $\beta(3)$ becomes

(5.2)
$$\beta(3) = \beta_0(3) + \frac{b_2}{4} \mu_2(r) + \frac{b_3}{24} \mu_3(r) + \frac{b_4}{192} (\mu_4(r) + 3\mu_2^2(r)) + \cdots,$$

where

$$b_i = \left[\frac{d_i}{d\vec{r}^i} \, \beta_0(\sqrt{n} \, A_2 \vec{r}) \right]_{\vec{r} = d_2}.$$

The moments $\mu_i(r)$ are obtained from Hartley and Pearson [2]. Expression (5.2) is used to evaluate $\beta(3)$ for n=5 and n=10. For the sake of completeness the case n=2 is also included. In this case, the pdf of the range is

$$h(r) = \frac{1}{\sqrt{\pi}\sigma} e^{-(r^2/(4\sigma^2))}$$
 $(r > 0).$

Hence, by the standard convolution (see [4], p. 191).

$$g_{22}(\bar{r};\sigma) = 2 \int_0^{2\bar{r}} h(2\bar{r}-t) h(t) dt,$$

which reduces to

$$g_{22}(\bar{r};\sigma) = \frac{4}{\sqrt{2\pi}\sigma} e^{-(\bar{r}^2/(2\sigma^2))} \left[\Phi\left(\frac{\bar{r}}{\sigma}\right) - \Phi\left(-\frac{\bar{r}}{\sigma}\right) \right].$$

Hence

$$\beta(3) = \int_0^\infty g_{22}(\vec{r})\beta_0(\sqrt{2}A_2\vec{r}) d\vec{r}$$

$$= \int_0^\infty \frac{4}{\sqrt{2\pi}} e^{-\frac{1}{2}\hat{r}^2} [\Phi(\vec{r}) - \Phi(-\vec{r})] \cdot \left[\Phi\left(\frac{2A_2\vec{r}}{\sqrt{1+2\theta^2}}\right) - \Phi\left(-\frac{2A_2\vec{r}}{\sqrt{1+2\theta^2}}\right) \right] d\vec{r}.$$

 $1 - \beta(3)$ is then evaluated by numerical integration.

The results for m = 2 are summarized in Tables I and II below.

B. Case m=3. We find from (4.3) that the joint density of u and v is given by

(5.3)
$$f_3(u,v) = \frac{3!\sqrt{3}}{2\pi(1+n\theta^2)} \exp\left[-\frac{1}{2(1+n\theta^2)}(u^2-uv+v^2)\right] \text{ over } S',$$

where

S' is
$$\begin{cases} 0 < v < 2u, \\ 0 < u < 2v. \end{cases}$$

Then

$$\beta_0(k) = 2 \int_0^k du \int_{\frac{1}{2}u}^u f_3(u, v) dv,$$

by virtue of the fact that $f_3(u, v)$ is symmetric about the line u = v. This integral reduces to

(5.4)
$$\beta_0(k) = 6 \sqrt{\frac{3}{\pi}} \int_0^{k/(2\sqrt{1+n\theta^2})} e^{-3t^2} F_2(t) dt,$$

where $F_2(x)$ is defined by

$$F_2(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt.$$

 $F_n(x)$ is the cdf of the extreme deviation from the sample mean in samples of n from a N(0, 1) population. This function has been tabulated by Grubbs [3]. $\beta_0(3)$

TABLE I					TABLE II			
$\beta_0(3)$ for $m=2$				$\beta(3)$ for $m=2$				
heta	n = 2	n=5	n = 10	θ	$\vec{n} = 2$	n=5	n = 10	
0	1.00	1.00	1.00	0	.96	1.00	1.00	
.5	1.00	1.00	.98	.5	.94	.98	.96	
1.0	.99	.92	.80	1.0	.89	.89	.79	
1.5	.93	.77	. 62	1.5	.82	.75	.61	
2.0	.84	.64	.49	2.0	.75	.63	.49	
2.5	.75	.55	.40	2.5	. 67	.54	.40	
3.0	.67	.47	.34	3.0	.61	.46	.34	

is evaluated from (5.4) by numerical integration and $\beta(3)$ obtained from the series (3.7). The results for this case are summarized in Tables III and IV.

C. Case m = 4. From (4.3) we obtain the joint pdf of u_1 , u_2 , and u_3 as

(5.6)
$$h_4(u_1, u, v) = \frac{4! \sqrt{\frac{4}{2}}}{(2\pi)^{\frac{3}{2}} (1 + n\theta^2)^{3/2}} e^{-[u_1^2/(2(1+n\theta^2))]} e^{-[\Lambda_4/(2(1+n\theta^2))]} \text{ over } S,$$

where

$$\Lambda_4 = \frac{3}{2}(u^2 + v^2) - uv,
S is \begin{cases} u_1 > 0, u > 0, v > 0,
\sqrt{2} u_1 < 3v - u,
\sqrt{2} u_1 < 3u - v. \end{cases}$$

To obtain $f_4(u, v)$, the joint density of u and v, we integrate over the range of u_1 , with the following result

$$f_4(u,v) = \begin{cases} C_1 e^{-[\Lambda_4/(2(1+n\theta^2))]} \int_0^{(3v-u)/\sqrt{2}} e^{-[u_1^2/(2(1+n\theta^2))]} du, & \text{for } v < u < 3v, \\ C_1 e^{-[\Lambda_4/(2(1+n\theta^2))]} \int_0^{(3u-v)/\sqrt{2}} e^{-[u_1^2/(2(1+n\theta^2))]} du, & \text{for } u < v < 3u, \end{cases}$$

where

$$C_1 = \frac{4! \sqrt{\frac{4}{2}}}{[2\pi(1+n\theta^2)]^{3/2}}.$$

But

$$\int_0^{(3v-u)/\sqrt{2}} e^{-u_1^2/(2(1+n\theta^2))} du_1 = \sqrt{2} \sqrt{1+n\theta^2} \int_0^{(3v-u)/(2\sqrt{1+n\theta^2})} e^{-t^2} dt$$
$$= \sqrt{\frac{\pi}{2}} \sqrt{1+n\theta^2} F_2 \left(\frac{3v-u}{2\sqrt{1+n\theta^2}} \right).$$

TABLE III $\beta_0(3)$ for m = 3

TABLE IV $\beta(3)$ for m = 3

θ	n=2	n = 5	n = 10	θ	n = 5	n = 10
0	1.00	1.00	1.00	0	.99	1.00
.5	.99	.96	.88	.5	.94	.86
1.0	.92	.71	.48	1.0	.69	.48
1.5	.74	.45	.27	$\frac{1.5}{2.0}$.45	.27
$\frac{2.0}{5}$.56	.30	.17	$egin{array}{c} 2.0 \ 2.5 \end{array}$.30 $.21$.17
$egin{array}{c} 2.5 \ 3.0 \end{array}$	$\begin{array}{c} .42 \\ .32 \end{array}$	$.21 \\ .15$.08	3.0	.15	.08
3.0	.52	.10	.00	0.0	•10	

In exactly the same manner

$$\int_{\mathbf{0}}^{(3u-v)/\sqrt{2}} e^{-\left[u_1^2/(2(1+n\theta^2))\right]} du_1 = \sqrt{\frac{\pi}{2}} \sqrt{1+n\theta^2} F_2\left(\frac{3u-v}{2\sqrt{1+n\theta^2}}\right).$$

Therefore

$$f_4(u, v) = C_1 \sqrt{\frac{\pi}{2}} \sqrt{1 + n\theta^2} e^{-[\Lambda_4/(2(1+n\theta^2))]} G(u, v),$$

where

$$G(u, v) = \begin{cases} F_2\left(\frac{3u - v}{2\sqrt{1 + n\theta^2}}\right) & \text{for } u < v < 3u, \\ F_2\left(\frac{3v - u}{2\sqrt{1 + n\theta^2}}\right) & \text{for } v < u < 3v. \end{cases}$$

Then

$$\beta_0(k) = 2 \int_0^k du \int_{u/3}^u f_4(u, v) du,$$

since $f_4(u, v)$ is symmetric in u and v. After some reduction we find

(5.7)
$$\beta_0(k) = 12 \frac{\sqrt{\frac{4}{3}}}{\sqrt{2\pi}} \int_0^{2k/(3\sqrt{1+n\theta^2})} e^{-(3t^2)/2} F_3(t) dt,$$

where

$$F_3(t) = \frac{3\sqrt{3}}{2\sqrt{\pi}} \int_0^t e^{-(3x^2/4)} F_2\left(\frac{3x}{2}\right) dx.$$

As before, $\beta_0(k)$ is evaluated by integrating (5.7) numerically and $\beta(3)$ is obtained from the series expansion. The results for this case are summarized in Tables V and VI.

TABLE V $\beta_0(3)$ for m=4

TABLE VI $\beta(3)$ for m = 4

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θ	n=2	n=5	n = 10	θ	n = 5	n=10
0	1.00	1.00	1.00	. 0	.99	1.00
.5	.98	.91	.76	.5	.87	.74
1.0	.82	.52	.27	1.0	.51	.27
1.5	.56	.25	.11	1.5	.26	.11
2.0	.34	.12	.05	2.0	.13	.05
2.5	.22	.07	.03	2.5	.07	.03
3.0	.14	.05	.02	3.0	.05	.02

D. Case m > 4. In this section we derive upper and lower bounds for $\beta_0(k)$ and $\beta(3)$. Recalling that $\beta_0(k) = P(u < k, v < k)$ we immediately obtain the upper bound $\beta_0(k) \le P(u < k)$. But since $u = (\bar{x}_{(m)} - \bar{x})/(\sigma/\sqrt{n})$, we see that $u/\sqrt{1 + n\theta^2}$ is distributed as the extreme deviation from the sample mean in samples of m from a N(0, 1) population. Hence, using Grubbs' notation [3]

(5.8)
$$\beta_0(k) \leq F_m \left(\frac{k}{\sqrt{1 + n\theta^2}} \right).$$

It follows that

(5.9)
$$\beta(3) = \int_0^\infty g_{mn}(\bar{r})\beta_0(\sqrt{n} A_2 \bar{r}) d\bar{r} \le \int_0^\infty g_{mn}(\bar{r})F_m\left(\frac{\sqrt{n} A_2 \bar{r}}{\sqrt{1 + n\theta^2}}\right) d\bar{r}.$$

(5.9) is then expanded in a Taylor's series with remainder by the method of Section 3.

To obtain a lower bound, we have from elementary probability considerations P(u < k or v < k) = P(u < k) + P(v < k) - P(u < k, v < k), or

(5.10)
$$P(u < k, v < k) = P(u < k) + P(v < k) - P(u < k \text{ or } v < k)$$
.

Since the last term in (5.10) cannot exceed unity we have

$$P(u < k, v < k) = \beta_0(k) \ge P(u < k) + P(v < k) - 1.$$

But

$$P(u < k) = P(v < k) = F_m \left(\frac{k}{\sqrt{1 + n\theta^2}}\right).$$

TABLE VII Bounds on $\beta_0(3)$

θ	m	= 5	m=10		
v	n = 5	n = 10	n=5	n = 10	
0	1.00	1.00	.98`.99	.98 .99	
.5	.87 .94				
1.5		.00 .12	.00 .06	.00 .01	
2.0	.00 .14	.00 .05	.00 .01		
2.5	.00 .07	.00 .02			
3.0	.00 .04	.00 .01			
θ	m =	= 15	m	m = 20	
	n=5	n=10 $n=5$		n = 10	
0	.97 .98	.97 .98	.96 .98	.96 .98	
.75			.00 .26	.00 .04	
1.0	.00 .13	.00 .02	.00 .06		
1.25			.00 .01		
1.5	.00 .01				
		m = 25			
θ		n = 5		n = 10	
0	0			.95 .97	
.25		.80 .91			
.7	5	.00 .18		.00 .02	
1,0	0	.00 .03			

Therefore

(5.11)
$$\beta_0(k) \ge 2F_m \left(\frac{k}{\sqrt{1 + n\theta^2}} \right) - 1.$$

The corresponding lower bound on $\beta(3)$ becomes

(5.12)
$$\beta(3) \geq \int_0^\infty g_{mn}(\bar{r}) \left[2F_m \left(\frac{\sqrt{n} A_2 \bar{r}}{\sqrt{1 + n\theta^2}} \right) - 1 \right] d\bar{r},$$

which is again evaluated by a Taylor expansion. The results given in Tables VII and VIII do not include certain intermediate values of θ in the range 0.25 to 1.50 because the lower bounds (5.11) and (5.12) are very weak in this range.

TABLE VIII Bounds on $\beta(3)$

		Bounds on p(o	')		
в	m	= 5	m = 10		
v	n = 5	n = 10	n = 5	n = 10	
0	.99	1.00	.97 .99	.98 .99	
.5	.81 .99				
1.5		.00 .12	.00 .06	.00 .01	
2.0	.00 .14	.00 .05	.00 .01		
2.5	.00 .07	.00 .02			
3.0	.00 .04	.00 .01			
θ	m	= 15	m = 20		
	n = 5	n = 10	n = 5	n = 10	
0	.96 .98	.96 .98	.94 .97	.95 .98	
.75			.00 .27	.00 .04	
1.0	.00 .13	.00 .02	.00 .06		
1.25			.00 .01		
1.5	.00 .01				
		m = 25			
θ		n = 5		n = 10	
0		.94 .97		.94 .97	
.2	25	.80 .90			
. 7	75	.00 .18		.00 .02	
1.0	00	.00 .03			

An important feature of Tables VII and VIII is the close agreement between corresponding values of $\beta_0(3)$ and $\beta(3)$. Our ignorance of σ is of little consequence so far as these results are concerned.

6. Bounds on the remainder term. In each of the Taylor expansions used in Section 5, there is a remainder term of the form

$$R = \int_0^\infty \frac{b_{p+1}(\xi)}{(p+1)!} (\bar{r} - d_2)^{p+1} g_{mn}(\bar{r}) d\bar{r}.$$

In order to determine a bound on R, we note that

$$|R| \leq \int_{0}^{\infty} \frac{|b_{p+1}(\xi)|}{(p+1)!} |\bar{r} - d_{2}|^{p+1} g_{mn}(\bar{r}) d\bar{r}$$

$$\leq \frac{\operatorname{Max} |b_{p+1}(\xi)|}{(p+1)!} \int_{0}^{\infty} |\bar{r} - d_{2}|^{p+1} g_{mn}(\bar{r}) d\bar{r}.$$

If we restrict p to be an odd integer, we have

(6.1)
$$|R| \leq \frac{\operatorname{Max} |b_{p+1}(\xi)|}{(p+1)!} \mu_{p+1}(\bar{r}).$$

In practically all cases given in the preceding tables, a sufficient number of terms of the series (3.7) is used to insure that the bound (6.1) does not exceed 0.005. In isolated instances where this is not possible; terms up to and including $b_6/6! \mu_6(\bar{r})$ are employed.

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