

Research Article

Solutions of Fractional Konopelchenko-Dubrovsky and Nizhnik-Novikov-Veselov Equations Using a Generalized Fractional Subequation Method

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A new generalized fractional subequation method based on the relationship of fractional coupled equations is proposed. This method is applied to the space-time fractional coupled Konopelchenko-Dubrovsky equations and Nizhnik-Novikov-Veselov equations. As a result, many exact solutions are obtained including hyperbolic function solutions, trigonometric function solutions, and rational solutions. It is observed that the proposed approach provides a simple and reliable tool for solving many other fractional coupled differential equations.

1. Introduction

Fractional calculus is one of the generalizations of ordinary calculus. Generally speaking, there are two kinds of fractional derivatives. One is nonlocal fractional derivative [1, 2], that is, Caputo derivative and Riemann-Liouville derivative which have been used successfully in various fields of science and engineering. The other one is the local fractional derivative, that is, Kolwankar-Gangal (K-G) derivative [3, 4], Chen's fractal derivative [5, 6], Cresson's derivative [7], and Jumarié's modified Riemann-Liouville derivative [8]. At the same time, fractional differential equations have attracted much attention in a variety of applied sciences. However, we have difficulty in finding exact analytical solutions [9–12] of fractional differential equations that appear more and more frequently in different research areas and engineering applications. So, numerical methods have been used to handle these equations, and some semianalytical techniques [13–16] have also largely been used to solve these equations.

Based on homogeneous balance principle [17], Jumarié's modified Riemann-Liouville derivative [8], and symbolic computation, S. Zhang and H.-Q. Zhang proposed a fractional subequation method to search for explicit solutions of FDEs. By using this method, S. Zhang and H.-Q. Zhang

successfully obtained some exact solutions of space-time fractional biological population model and fractional Fokas equation [18]. Jafari et al. have given some solutions of the fractional Cahn-Hilliard and Klein-Gordon equations [19]. Tang et al. [20] proposed a generalized fractional subequation method for fractional differential equations with variable coefficients. Guo et al. [21] and Zhao et al. [22] both improved the fractional subequation and applied to space-time fractional coupled differential equations; in their paper, they choose two or three appropriate ansatz. However, for some coupled equations [23, 24], even some fractional coupled equations, we can get the relationship of the functions. So, we propose a new generalized fractional subequation which chooses only one appropriate ansatz and use this method to solve the following two NFDEs.

(1) The space-time fractional coupled Konopelchenko-Dubrovsky (KD) equations in the form

$$D_t^\alpha u - D_x^{3\alpha} u - 6buD_x^\alpha u + \frac{3}{2}a^2 u^2 D_x^\alpha u - 3D_y^\alpha v + 3aD_x^\alpha uv = 0,$$
$$D_y^\alpha u = D_x^\alpha v, \quad (1)$$

which is a transformed generalization of the KD equations [25], where a and b are real constants. Equation (1) is a fractional evolution equation on two spatial dimensions and one temporal, where x and y are the running coordinates, t is the time, and $u = u(x, y, t)$ and $v = v(x, y, t)$ are the amplitudes of the relevant waves. $D_t^\alpha(\cdot)$ and $D_x^\alpha(\cdot)$ are Jumarie's modified Riemann-Liouville derivative of order α defined in Section 2, $0 < \alpha \leq 1$. The Jumarie's modified Riemann-Liouville derivative has many interesting properties. The KD equations can be used to describe the ocean dynamics, fluid mechanics, and plasma physics, and the Gardner, KP, modified KP, and KD equations are all the special cases of (1). When $\alpha = 1$, $u_y = 0$, (1) is the Gardner equation (combined KdV and modified equation). When $\alpha = 1$, $a = 0$, (1) is the well-known Kadomtsev-Petviashvili (KP) equation, and modified KP equation reads from (1) for $\alpha = 1$, $b = 0$.

(2) The space-time fractional coupled Nizhnik-Novikov-Veselov (NNV) equation in the form

$$\begin{aligned}
 D_t^\alpha u &= AD_x^{3\alpha} u + BD_y^{3\alpha} u - 3AuD_x^\alpha v - 3AvD_x^\alpha u \\
 &\quad - 3BuD_y^\alpha w - 3BwD_y^\alpha u, \\
 D_x^\alpha u &= D_y^\alpha v, \\
 D_y^\alpha u &= D_x^\alpha w,
 \end{aligned} \tag{2}$$

where $0 < \alpha \leq 1$, A and B are given constants satisfying $A + B \neq 0$, and u , v , and w are the functions of (x, y, t) , the case when $\alpha \rightarrow 1$ was studied in [26]. NNV equations have been studied over several areas of physics including condense matter physics, fluid mechanics, plasma physics, and optics.

The rest of this paper is organized as follows. In Section 2, some basic definitions of Jumarie's modified Riemann-Liouville derivative and the main steps of the generalized fractional subequation method are given. In Section 3, we construct the exact solutions of above space-time fractional coupled equations via this new generalized method. Some conclusions and discussions are shown in Section 4.

2. Jumarie's Modified Riemann-Liouville Derivative and Generalized Fractional Subequation Method

The Jumarie's modified Riemann-Liouville derivative [8] of order α time-fractional derivative operator of order $\alpha > 0$ is defined as

$$D_t^\alpha f = \begin{cases} \frac{1}{\Gamma(1-\alpha)} \int_0^t (t-\xi)^{-\alpha-1} (f(\xi) - f(0)) d\xi, & \alpha < 0, \\ \frac{1}{\Gamma(1-\alpha)} \frac{d}{dt} \int_0^t (t-\xi)^{-\alpha} (f(\xi) - f(0)) d\xi, & 0 < \alpha < 1, \\ (f^{(n)}(t))^{\alpha-n}, & n \leq \alpha < n+1, n \geq 1. \end{cases} \tag{3}$$

Some properties for the proposed modified Riemann-Liouville derivative are listed in [8] as follows:

$$D_t^\alpha t^\delta = \frac{\Gamma(1+\delta)}{\Gamma(1+\delta-\alpha)} t^{\delta-\alpha}, \quad \delta > 0, \tag{4}$$

$$D_t^\alpha (f(t)g(t)) = g(t)D_t^\alpha f(t) + f(t)D_t^\alpha g(t), \tag{5}$$

$$D_t^\alpha f[g(t)] = f'_g[g(t)]D_t^\alpha g(t), \tag{6}$$

$$D_t^\alpha f[g(t)] = D_g^\alpha f[g(t)](g'(t))^\alpha. \tag{7}$$

The above equations play an important role in fractional calculus in the following sections.

we propose a generalized fractional subequation method; the essential steps of this method are described as follows.

Step 1. Suppose that NFDEs with independent variables $X = (x_1, x_2, x_3, \dots, x_m, t)$ are given by

$$\begin{aligned}
 P(u, v, u_t, u_{x_1}, \dots, v_t, v_{x_1}, \dots, D_t^\alpha u, D_{x_1}^\alpha u, \dots, \\
 D_t^\alpha v, D_{x_1}^\alpha v, \dots) &= 0, \quad 0 < \alpha \leq 1, \\
 Q(u, v, u_t, u_{x_1}, \dots, v_t, v_{x_1}, \dots, D_t^\alpha u, D_{x_1}^\alpha u, \dots, \\
 D_t^\alpha v, D_{x_1}^\alpha v, \dots) &= 0, \quad 0 < \alpha \leq 1,
 \end{aligned} \tag{8}$$

where $D_t^\alpha(\cdot)$ and $D_{x_1}^\alpha(\cdot)$ are Jumarie's modified Riemann-Liouville derivative with respect to t and x_1 , $u = u(x, t)$, $v = v(x, t)$ are unknown functions, P is a polynomial in u , v , and their various partial derivatives, Q is a polynomial in u , v , and their various partial derivatives, and the highest order derivatives and nonlinear terms are involved.

Step 2. By using the traveling wave transformations

$$\begin{aligned}
 u(x_1, \dots, x_m, t) &= u(\xi), \quad v(x_1, \dots, x_m, t) = v(\xi), \\
 \xi &= k_1 x_1 + \dots + k_m x_m + ct,
 \end{aligned} \tag{9}$$

where c is a constant to be determined later, the NFDE (7) is reduced to the following nonlinear fractional ordinary differential equation (ODE) for $u(\xi)$ and $v(\xi)$:

$$\begin{aligned}
 P(u, v, cu', k_1 u', \dots, cv', k_1 v', \dots, c^\alpha D_\xi^\alpha u, k_1^\alpha D_\xi^\alpha u, \dots, \\
 c^\alpha D_\xi^\alpha v, k_1^\alpha D_\xi^\alpha v, \dots) &= 0, \\
 Q(u, v, cu', k_1 u', \dots, cv', k_1 v', \dots, c^\alpha D_\xi^\alpha u, k_1^\alpha D_\xi^\alpha u, \dots, \\
 c^\alpha D_\xi^\alpha v, k_1^\alpha D_\xi^\alpha v, \dots) &= 0,
 \end{aligned} \tag{10}$$

Step 3. For some coupled equations, we get the relationship

$$v = f(u), \tag{11}$$

and substituting into (8), one has

$$\begin{aligned}
 Q(u, v, cu', k_1 u', \dots, cv', k_1 v', \dots, c^\alpha D_\xi^\alpha u, k_1^\alpha D_\xi^\alpha u, \dots, \\
 c^\alpha D_\xi^\alpha v, k_1^\alpha D_\xi^\alpha v, \dots) &= 0.
 \end{aligned} \tag{12}$$

Step 4. We suppose that (12) has the following solution:

$$u(\xi) = \sum_{i=-n}^{i=n} a_i \varphi^i, \tag{13}$$

where a_i ($i = -n, -n + 1, \dots, n - 1, n$) are constants to be determined later, n is a positive integer determined by balancing the highest order derivatives and nonlinear terms in (12) (see [17] for details), and $\varphi = \varphi(\xi)$ satisfies the following fractional Riccati equation:

$$D_\xi^\alpha \varphi(\xi) = \sigma + \varphi^2(\xi). \tag{14}$$

By using the generalized Exp-function method via Mittag-Leffler functions, S. Zhang and H.-Q. Zhang first obtained generalized hyperbolic and trigonometric functions of fractional Riccati equation [18], and the obtained five solutions of (14) are

$$\varphi(\xi) = \begin{cases} -\sqrt{-\sigma} \tanh_\alpha(\sqrt{-\sigma} \xi), & \sigma < 0, \\ -\sqrt{-\sigma} \coth_\alpha(\sqrt{-\sigma} \xi), & \sigma < 0, \\ \sqrt{\sigma} \tan_\alpha(\sqrt{\sigma} \xi), & \sigma > 0, \\ -\sqrt{\sigma} \cot_\alpha(\sqrt{\sigma} \xi), & \sigma > 0, \\ -\frac{\Gamma(1+\alpha)}{\xi^\alpha + \omega}, \omega = \text{const.}, & \sigma = 0, \end{cases} \tag{15}$$

where \tanh_α , \coth_α , \tan_α , and \cot_α are generalized hyperbolic and trigonometric functions defined in [18] as

$$\begin{aligned} \tanh_\alpha(x) &= \frac{\sinh_\alpha(x)}{\cosh_\alpha(x)}, & \coth_\alpha(x) &= \frac{\cosh_\alpha(x)}{\sinh_\alpha(x)}, \\ \sinh_\alpha(x) &= \frac{E_\alpha(x^\alpha) - E_\alpha(-x^\alpha)}{2}, \\ \cosh_\alpha(x) &= \frac{E_\alpha(x^\alpha) + E_\alpha(-x^\alpha)}{2}, \\ \tan_\alpha(x) &= \frac{\sin_\alpha(x)}{\cos_\alpha(x)}, & \cot_\alpha(x) &= \frac{\cos_\alpha(x)}{\sin_\alpha(x)}, \\ \sin_\alpha(x) &= \frac{E_\alpha(ix^\alpha) - E_\alpha(-ix^\alpha)}{2i}, \\ \cos_\alpha(x) &= \frac{E_\alpha(ix^\alpha) + E_\alpha(-ix^\alpha)}{2}, \end{aligned} \tag{16}$$

where $E_\alpha(z) = \sum_{k=0}^{\infty} (z^k / \Gamma(1 + k\alpha))$ is the Mittag-Leffler function.

Step 5. Substituting (13) into (12) along with (14) and using the properties of Jumarie's modified Riemann-Liouville derivative (4)–(7), we can get a polynomial in $\varphi(\xi)$. Setting all the coefficients of φ^k ($k = 0, 1, 2, \dots, -1, -2, \dots$) to zero yields a set of overdetermined nonlinear algebraic equations for c, k_i ($i = 1, 2, \dots, m$), a_j ($j = -n, -n + 1, \dots, n - 1, n$).

Step 6. Take advantage of the known solutions of (14) to get the solutions of the fractional coupled NPDEs in concern.

3. Solutions of Fractional Coupled KD Equation and NNV Equations

In this section, we apply the generalized fractional subequation method for solving the NPDEs (1) and (2).

Example 1. The space-time fractional KD equations. By considering the traveling wave transformations $u = u(\xi)$, $v = v(\xi)$, and $\xi = lx + my + nt$, (1) can be reduced to the following nonlinear fractional ODEs:

$$n^\alpha D_\xi^\alpha u - l^{3\alpha} D_\xi^{3\alpha} u - 6bl^\alpha u D_\xi^\alpha u + \frac{3}{2} a^2 l^\alpha u^2 D_\xi^\alpha u \tag{17}$$

$$- 3m^\alpha D_\xi^\alpha v + 3al^\alpha v D_\xi^\alpha u = 0,$$

$$m^\alpha D_\xi^\alpha u = l^\alpha D_\xi^\alpha v. \tag{18}$$

From (18) and using the definition of Jumarie's modified Riemann-Liouville derivative, one gets

$$v = \frac{m^\alpha}{l^\alpha} u + c, \tag{19}$$

where c is the arbitrary constant. Substituting (19) into (17), one obtains

$$\left(n^\alpha - 6bl^\alpha u + \frac{3}{2} a^2 l^\alpha u^2 - 3 \frac{m^{2\alpha}}{l^\alpha} + 3am^\alpha u + 3al^\alpha c \right) \tag{20}$$

$$\times D_\xi^\alpha u - l^{3\alpha} D_\xi^{3\alpha} u = 0.$$

By balancing the highest order derivative terms and nonlinear terms in (20), we suppose that (20) has the following formal solution:

$$u(\xi) = a_0 + a_1 \varphi(\xi) + \frac{a_2}{\varphi(\xi)}. \tag{21}$$

Substituting (21) into (20) along with (14) and collecting the coefficients of φ^i and setting them to be zero, we can get a set of algebraic equation about l, m, n, c, a_0, a_1 , and a_2 . Solving the algebraic equations by Mathematica, we have the following.

Case 1. One has

$$\begin{aligned} a_0 &= \frac{2b - am^\alpha l^{-\alpha}}{a^2}, & a_1 &= 0, & a_2 &= -\frac{2l^\alpha \sigma}{\sqrt{a}}, \\ n &= \left((-12abm^\alpha + 9a^2 m^{2\alpha} l^{-\alpha} + 12b^2 l6\alpha - 6ba^3 cl^\alpha \right. \\ &\quad \left. + 4a^3 l^{3\alpha} \sigma) \times (2a^2)^{-1} \right)^{1/\alpha}. \end{aligned} \tag{22}$$

Case 2. One has

$$\begin{aligned} a_0 &= \frac{2b - am^\alpha l^{-\alpha}}{a^2}, & a_1 &= 0, & a_2 &= \frac{2l^\alpha \sigma}{\sqrt{a}}, \\ n &= \left((-12abm^\alpha + 9a^2 m^{2\alpha} l^{-\alpha} + 12b^2 l6\alpha \right. \\ &\quad \left. - 6ba^3 cl^\alpha + 4a^3 l^{3\alpha} \sigma) \times (2a^2)^{-1} \right)^{1/\alpha}. \end{aligned} \tag{23}$$

Case 3. One has

$$a_0 = \frac{2b - am^\alpha l^{-\alpha}}{a^2}, \quad a_1 = \frac{2l^\alpha}{\sqrt{a}}, \quad a_2 = 0,$$

$$n = \left((-12abm^\alpha + 9a^2m^{2\alpha}l^{-\alpha} + 12b^2l6\alpha - 6ba^3cl^\alpha + 4a^3l^{3\alpha}\sigma) \times (2a^2)^{-1} \right)^{1/\alpha}. \quad (24)$$

Case 4. One has

$$a_0 = \frac{2b - am^\alpha l^{-\alpha}}{a^2}, \quad a_1 = -\frac{2l^\alpha}{\sqrt{a}}, \quad a_2 = 0,$$

$$n = \left((-12abm^\alpha + 9a^2m^{2\alpha}l^{-\alpha} + 12b^2l6\alpha - 6ba^3cl^\alpha + 4a^3l^{3\alpha}\sigma) \times (2a^2)^{-1} \right)^{1/\alpha}. \quad (25)$$

Case 5. One has

$$a_0 = \frac{2b - am^\alpha l^{-\alpha}}{a^2}, \quad a_1 = -\frac{2l^\alpha}{\sqrt{a}}, \quad a_2 = -\frac{2l^\alpha \sigma}{\sqrt{a}},$$

$$n = \left((-12abm^\alpha + 9a^2m^{2\alpha}l^{-\alpha} + 12b^2l6\alpha - 6ba^3cl^\alpha - 8a^3l^{3\alpha}\sigma) \times (2a^2)^{-1} \right)^{1/\alpha}. \quad (26)$$

Case 6. One has

$$a_0 = \frac{2b - am^\alpha l^{-\alpha}}{a^2}, \quad a_1 = \frac{2l^\alpha}{\sqrt{a}}, \quad a_2 = -\frac{2l^\alpha \sigma}{\sqrt{a}},$$

$$n = \left((-12abm^\alpha + 9a^2m^{2\alpha}l^{-\alpha} + 12b^2l6\alpha - 6ba^3cl^\alpha + 16a^3l^{3\alpha}\sigma) \times (2a^2)^{-1} \right)^{1/\alpha}. \quad (27)$$

Case 7. One has

$$a_0 = \frac{2b - am^\alpha l^{-\alpha}}{a^2}, \quad a_1 = -\frac{2l^\alpha}{\sqrt{a}}, \quad a_2 = \frac{2l^\alpha \sigma}{\sqrt{a}},$$

$$n = \left((-12abm^\alpha + 9a^2m^{2\alpha}l^{-\alpha} + 12b^2l6\alpha - 6ba^3cl^\alpha + 16a^3l^{3\alpha}\sigma) \times (2a^2)^{-1} \right)^{1/\alpha}. \quad (28)$$

Case 8. One has

$$a_0 = \frac{2b - am^\alpha l^{-\alpha}}{a^2}, \quad a_1 = \frac{2l^\alpha}{\sqrt{a}}, \quad a_2 = \frac{2l^\alpha \sigma}{\sqrt{a}},$$

$$n = \left((-12abm^\alpha + 9a^2m^{2\alpha}l^{-\alpha} + 12b^2l6\alpha - 6ba^3cl^\alpha - 9a^3l^{3\alpha}\sigma) \times (2a^2)^{-1} \right)^{1/\alpha}. \quad (29)$$

Using Case 1, (21), and the solutions of (14), we can find the following exact solutions of NFDEs (1):

$$u_1 = -\frac{2\sqrt{-\sigma} l^\alpha}{\sqrt{a} \tanh_\alpha(-\sqrt{-\sigma} \xi)} + \frac{2bl^\alpha - am^\alpha}{a^2 l^\alpha},$$

$$v_1 = -\frac{2\sqrt{-\sigma} m^\alpha}{\sqrt{a} \tanh_\alpha(-\sqrt{-\sigma} \xi)} + \frac{2bm^\alpha l^\alpha - am^{2\alpha}}{a^2 l^{2\alpha}} + c, \quad (30)$$

where $\sigma < 0$, $\xi = lx + my + nt$,

$$u_2 = -\frac{2\sqrt{-\sigma} l^\alpha}{\sqrt{a} \coth_\alpha(-\sqrt{-\sigma} \xi)} + \frac{2bl^\alpha - am^\alpha}{a^2 l^\alpha},$$

$$v_2 = -\frac{2\sqrt{-\sigma} m^\alpha}{\sqrt{a} \coth_\alpha(-\sqrt{-\sigma} \xi)} + \frac{2bm^\alpha l^\alpha - am^{2\alpha}}{a^2 l^{2\alpha}} + c, \quad (31)$$

where $\sigma < 0$, $\xi = lx + my + nt$,

$$u_3 = -\frac{2\sqrt{\sigma} l^\alpha}{\sqrt{a} \tan_\alpha(\sqrt{\sigma} \xi)} + \frac{2bl^\alpha - am^\alpha}{a^2 l^\alpha},$$

$$v_3 = -\frac{2\sqrt{\sigma} m^\alpha}{\sqrt{a} \tan_\alpha(\sqrt{\sigma} \xi)} + \frac{2bm^\alpha l^\alpha - am^{2\alpha}}{a^2 l^{2\alpha}} + c, \quad (32)$$

where $\sigma > 0$, $\xi = lx + my + nt$,

$$u_4 = \frac{2\sqrt{\sigma} l^\alpha}{\sqrt{a} \cot_\alpha(\sqrt{\sigma} \xi)} + \frac{2bl^\alpha - am^\alpha}{a^2 l^\alpha},$$

$$v_4 = \frac{2\sqrt{\sigma} m^\alpha}{\sqrt{a} \cot_\alpha(\sqrt{\sigma} \xi)} + \frac{2bm^\alpha l^\alpha - am^{2\alpha}}{a^2 l^{2\alpha}} + c, \quad (33)$$

where $\sigma > 0$, $\xi = lx + my + nt$,

$$u_5 = \frac{2\sigma l^\alpha (\omega + \xi^\alpha)}{\sqrt{a} \Gamma(1 + a)} + \frac{2bl^\alpha - am^\alpha}{a^2 l^\alpha},$$

$$v_5 = \frac{2\sigma m^\alpha (\omega + \xi^\alpha)}{\sqrt{a} \Gamma(1 + a)} + \frac{2bm^\alpha l^\alpha - am^{2\alpha}}{a^2 l^{2\alpha}} + c, \quad (34)$$

where $\sigma = 0$, $\xi = lx + my + nt$. And $n = ((-12abm^\alpha + 9a^2m^{2\alpha}l^{-\alpha} + 12b^2l6\alpha - 6ba^3cl^\alpha + 4a^3l^{3\alpha}\sigma)/2a^2)^{1/\alpha}$, l, m, c , and ω are arbitrary constants.

From Cases 2, 3, 4, 5, 6, 7, and 8, we obtain many other exact solutions of (1). Here, we omit them for simplicity.

For $\alpha = 1$, generalized hyperbolic function solutions and generalized trigonometric function solutions degrade into hyperbolic function solutions and trigonometric function solutions. We stress on the fact that when $\alpha \rightarrow 1$ these obtained exact solutions including solitary solutions and rational solutions give the ones of the standard form equation of the space-time fractional KD equation (1).

Example 2 (The space-time fractional NNV equations). By considering the traveling wave transformations $u = u(\xi)$,

$v = v(\xi)$, and $\xi = lx + my + nt$, (2) can be reduced to the following nonlinear fractional ODEs:

$$n^\alpha D_\xi^\alpha u = Al^{3\alpha} D_\xi^{3\alpha} u + Bm^{3\alpha} u D_\xi^{3\alpha} u - 3Al^\alpha u D_\xi^\alpha v - 3Al^\alpha v D_\xi^\alpha u - 3Bm^\alpha u D_\xi^\alpha w - 3Bm^\alpha w D_\xi^\alpha u, \tag{35}$$

$$l^\alpha D_\xi^\alpha u = m^\alpha D_\xi^\alpha v, \tag{36}$$

$$m^\alpha D_\xi^\alpha u = l^\alpha D_\xi^\alpha w. \tag{37}$$

From (36)-(37) and using the definition of Jumarie's modified Riemann-Liouville derivative, one gets

$$v = \frac{l^\alpha}{m^\alpha} u + c_1, \tag{38}$$

$$w = \frac{m^\alpha}{l^\alpha} u + c_2,$$

where c_1 and c_2 are arbitrary constants. Substituting (38) into (35), one obtains

$$\left(n^\alpha + 6A \frac{l^{2\alpha}}{m^\alpha} u + 3Al^\alpha c_1 + 6b \frac{m^{2\alpha}}{l^\alpha} u + 3Bm^\alpha c_2 \right) \times D_\xi^\alpha u - (Al^{3\alpha} + Bm^{3\alpha}) D_\xi^{3\alpha} u = 0. \tag{39}$$

By balancing the highest order derivative terms and nonlinear terms in (39), we suppose that (39) has the following formal solution:

$$u(\xi) = b_0 + b_1 \varphi(\xi) + b_2 \varphi^2(\xi) + \frac{b_3}{\varphi(\xi)} + \frac{b_4}{\varphi^2(\xi)}. \tag{40}$$

Substituting (40) into (39) along with (14), and collecting the coefficients of φ^j and setting them to be zero, we can get a set of algebraic equation about $l, m, n, c_1, c_2, b_0, b_1, b_2, b_3,$ and b_4 . Solving the algebraic equations by Mathematica, we have

Case 1. One has

$$b_0 = \frac{m^\alpha l^\alpha (8Al^{3\alpha} \sigma + 8Bm^{3\alpha} \sigma - 3Ac_1 l^\alpha - 3Bc_2 m^\alpha - n^\alpha)}{6Al^{3\alpha} + 6Bm^{3\alpha}},$$

$$b_1 = 0, \quad b_2 = -2m^\alpha l^\alpha,$$

$$b_3 = 0, \quad b_4 = 2m^\alpha l^\alpha \sigma^2. \tag{41}$$

Case 2. One has

$$b_0 = \frac{m^\alpha l^\alpha (8Al^{3\alpha} \sigma + 8Bm^{3\alpha} \sigma - 3Ac_1 l^\alpha - 3Bc_2 m^\alpha - n^\alpha)}{6Al^{3\alpha} + 6Bm^{3\alpha}},$$

$$b_1 = 0, \quad b_2 = 0,$$

$$b_3 = 0, \quad b_4 = 2m^\alpha l^\alpha \sigma^2. \tag{42}$$

Case 3. One has

$$b_0 = \frac{m^\alpha l^\alpha (8Al^{3\alpha} \sigma + 8Bm^{3\alpha} \sigma - 3Ac_1 l^\alpha - 3Bc_2 m^\alpha - n^\alpha)}{6Al^{3\alpha} + 6Bm^{3\alpha}},$$

$$b_1 = 0, \quad b_2 = 2m^\alpha l^\alpha,$$

$$b_3 = 0, \quad b_4 = 0. \tag{43}$$

Using Case 1, (40), and the solutions of (14), we can find the following exact solutions of NFDEs (2):

$$u_1 = -2m^\alpha l^\alpha \sigma \tanh_\alpha^2(\sqrt{-\sigma} \xi) - \frac{2m^\alpha l^\alpha \sigma}{\tanh_\alpha^2(\sqrt{-\sigma} \xi)} + \frac{m^\alpha l^\alpha (8Al^{3\alpha} \sigma + 8Bm^{3\alpha} \sigma - 3Bc_2 m^\alpha - 3Ac_1 l^\alpha - n^\alpha)}{6Al^{3\alpha} + 6Bm^{3\alpha}},$$

$$v_1 = -2l^{2\alpha} \sigma \tanh_\alpha^2(\sqrt{-\sigma} \xi) - \frac{2l^{2\alpha} \sigma}{\tanh_\alpha^2(\sqrt{-\sigma} \xi)} + (m^\alpha l^\alpha (8Al^{5\alpha} \sigma + 8Bl^{2\alpha} m^{3\alpha} \sigma - 3Bc_2 l^{2\alpha} m^\alpha - 3Ac_1 l^{3\alpha} - l^{2\alpha} n^\alpha) \times (6Al^{3\alpha} + 6Bm^{3\alpha})^{-1} + c_1),$$

$$w_1 = -2m^{2\alpha} \sigma \tanh_\alpha^2(\sqrt{-\sigma} \xi) - \frac{2m^{2\alpha} \sigma}{\tanh_\alpha^2(\sqrt{-\sigma} \xi)} + (m^\alpha l^\alpha (8Al^{3\alpha} m^{2\alpha} \sigma + 8Bm^{5\alpha} \sigma - 3Bc_2 m^{3\alpha} m^\alpha - 3Ac_1 l^\alpha m^{2\alpha} - m^{2\alpha} n^\alpha) \times (6Al^{3\alpha} + 6Bm^{3\alpha})^{-1}) + c_2, \tag{44}$$

where $\sigma < 0, \xi = lx + my + nt$,

$$u_2 = -2m^\alpha l^\alpha \sigma \coth_\alpha^2(\sqrt{-\sigma} \xi) - \frac{2m^\alpha l^\alpha \sigma}{\coth_\alpha^2(\sqrt{-\sigma} \xi)} + \frac{m^\alpha l^\alpha (8Al^{3\alpha} \sigma + 8Bm^{3\alpha} \sigma - 3Bc_2 m^\alpha - 3Ac_1 l^\alpha - n^\alpha)}{6Al^{3\alpha} + 6Bm^{3\alpha}},$$

$$v_2 = -2l^{2\alpha} \sigma \coth_\alpha^2(\sqrt{-\sigma} \xi) - \frac{2l^{2\alpha} \sigma}{\coth_\alpha^2(\sqrt{-\sigma} \xi)} + ((8Al^{5\alpha} \sigma + 8Bl^{2\alpha} m^{3\alpha} \sigma - 3Bc_2 l^{2\alpha} m^\alpha - 3Ac_1 l^{3\alpha} - l^{2\alpha} n^\alpha) \times (6Al^{3\alpha} + 6Bm^{3\alpha})^{-1}) + c_1,$$

$$\begin{aligned}
w_2 = & -2m^{2\alpha}\sigma\coth_\alpha^2(\sqrt{-\sigma}\xi) - \frac{2m^{2\alpha}\sigma}{\coth_\alpha^2(\sqrt{-\sigma}\xi)} \\
& + \left((8Al^{3\alpha}m^{2\alpha}\sigma + 8Bm^{5\alpha}\sigma - 3Bc_2m^{3\alpha}m^\alpha \right. \\
& \quad \left. - 3Ac_1l^\alpha m^{2\alpha} - m^{2\alpha}n^\alpha) \right. \\
& \quad \left. \times (6Al^{3\alpha} + 6Bm^{3\alpha})^{-1} \right) + c_2,
\end{aligned} \tag{45}$$

where $\sigma < 0$, $\xi = lx + my + nt$,

$$\begin{aligned}
u_3 = & 2m^\alpha l^\alpha \sigma \tan_\alpha^2(\sqrt{\sigma}\xi) + \frac{2m^\alpha l^\alpha \sigma}{\tan_\alpha^2(\sqrt{\sigma}\xi)} \\
& + \frac{m^\alpha l^\alpha (8Al^{3\alpha}\sigma + 8Bm^{3\alpha}\sigma - 3Bc_2m^\alpha - 3Ac_1l^\alpha - n^\alpha)}{6Al^{3\alpha} + 6Bm^{3\alpha}}, \\
v_3 = & 2l^{2\alpha}\sigma \tan_\alpha^2(\sqrt{\sigma}\xi) + \frac{2l^{2\alpha}\sigma}{\tan_\alpha^2(\sqrt{\sigma}\xi)} \\
& + \left((8Al^{5\alpha}\sigma + 8Bl^{2\alpha}m^{3\alpha}\sigma - 3Bc_2l^{2\alpha}m^\alpha \right. \\
& \quad \left. - 3Ac_1l^{3\alpha} - l^{2\alpha}n^\alpha) \right. \\
& \quad \left. \times (6Al^{3\alpha} + 6Bm^{3\alpha})^{-1} \right) + c_1, \\
w_3 = & 2m^{2\alpha}\sigma \tan_\alpha^2(\sqrt{\sigma}\xi) + \frac{2m^{2\alpha}\sigma}{\tan_\alpha^2(\sqrt{\sigma}\xi)} \\
& + \left((8Al^{3\alpha}m^{2\alpha}\sigma + 8Bm^{5\alpha}\sigma - 3Bc_2m^{3\alpha}m^\alpha \right. \\
& \quad \left. - 3Ac_1l^\alpha m^{2\alpha} - m^{2\alpha}n^\alpha) \right. \\
& \quad \left. \times (6Al^{3\alpha} + 6Bm^{3\alpha})^{-1} \right) + c_2,
\end{aligned} \tag{46}$$

where $\sigma > 0$, $\xi = lx + my + nt$,

$$\begin{aligned}
u_4 = & 2m^\alpha l^\alpha \sigma \cot_\alpha^2(\sqrt{\sigma}\xi) + \frac{2m^\alpha l^\alpha \sigma}{\cot_\alpha^2(\sqrt{\sigma}\xi)} \\
& + \frac{m^\alpha l^\alpha (8Al^{3\alpha}\sigma + 8Bm^{3\alpha}\sigma - 3Bc_2m^\alpha - 3Ac_1l^\alpha - n^\alpha)}{6Al^{3\alpha} + 6Bm^{3\alpha}}, \\
v_4 = & 2l^{2\alpha}\sigma \cot_\alpha^2(\sqrt{\sigma}\xi) + \frac{2l^{2\alpha}\sigma}{\cot_\alpha^2(\sqrt{\sigma}\xi)} \\
& + \left((8Al^{5\alpha}\sigma + 8Bl^{2\alpha}m^{3\alpha}\sigma - 3Bc_2l^{2\alpha}m^\alpha \right. \\
& \quad \left. - 3Ac_1l^{3\alpha} - l^{2\alpha}n^\alpha) \right. \\
& \quad \left. \times (6Al^{3\alpha} + 6Bm^{3\alpha})^{-1} \right) + c_1,
\end{aligned}$$

$$\begin{aligned}
w_4 = & 2m^{2\alpha}\sigma \cot_\alpha^2(\sqrt{\sigma}\xi) + \frac{2m^{2\alpha}\sigma}{\cot_\alpha^2(\sqrt{\sigma}\xi)} \\
& + \left((8Al^{3\alpha}m^{2\alpha}\sigma + 8Bm^{5\alpha}\sigma - 3Bc_2m^{3\alpha}m^\alpha \right. \\
& \quad \left. - 3Ac_1l^\alpha m^{2\alpha} - m^{2\alpha}n^\alpha) \right. \\
& \quad \left. \times (6Al^{3\alpha} + 6Bm^{3\alpha})^{-1} \right) + c_2,
\end{aligned} \tag{47}$$

where $\sigma > 0$, $\xi = lx + my + nt$,

$$\begin{aligned}
u_5 = & \frac{2\sigma^2 l^\alpha m^\alpha (\omega + \xi^\alpha)^2}{\Gamma^2(1+a)} + \frac{2l^\alpha m^\alpha \Gamma^2(1+a)}{(\omega + \xi^\alpha)^2} \\
& + \frac{m^\alpha l^\alpha (8Al^{3\alpha}\sigma + 8Bm^{3\alpha}\sigma - 3Bc_2m^\alpha - 3Ac_1l^\alpha - n^\alpha)}{6Al^{3\alpha} + 6Bm^{3\alpha}}, \\
v_5 = & \frac{2\sigma^2 l^\alpha (\omega + \xi^\alpha)^2}{\Gamma^2(1+a)} + \frac{2l^{2\alpha}\Gamma^2(1+a)}{(\omega + \xi^\alpha)^2} \\
& + \left((8Al^{5\alpha}\sigma + 8Bl^{2\alpha}m^{3\alpha}\sigma - 3Bc_2m^\alpha l^{2\alpha} - 3Ac_1l^{3\alpha} \right. \\
& \quad \left. - l^{2\alpha}n^\alpha) \right. \\
& \quad \left. \times (6Al^{3\alpha} + 6Bm^{3\alpha})^{-1} \right) + c_1, \\
w_5 = & \frac{2\sigma^2 l^\alpha (\omega + \xi^\alpha)^2}{\Gamma^2(1+a)} + \frac{2l^{2\alpha}\Gamma^2(1+a)}{(\omega + \xi^\alpha)^2} \\
& + \left((8Al^{3\alpha}m^{2\alpha}\sigma + 8Bl^{5\alpha}m^{3\alpha}\sigma - 3Bc_2m^{3\alpha} \right. \\
& \quad \left. - 3Ac_1l^\alpha m^{2\alpha} - m^{2\alpha}n^\alpha) \right. \\
& \quad \left. \times (6Al^{3\alpha} + 6Bm^{3\alpha})^{-1} \right) + c_2,
\end{aligned} \tag{48}$$

where $\sigma = 0$, $\xi = lx + my + nt$. And l , m , c , and ω are arbitrary constants, \tanh_α , \coth_α , \tan_α , and \cot_α are generalized hyperbolic and trigonometric functions.

From Cases 2 and 3, we obtain many other exact solutions of (2). Here, we omit them for simplicity, too.

As $\alpha \rightarrow 1$, solutions (44)–(48) obtained above become the ones of the standard form equation of the NNV model, and the solutions cannot be directly constructed by other methods.

4. Conclusion

In the paper, based on the relationship of the fractional coupled equations and the properties of the Jumarie's modified Riemann-Liouville derivative, we proposed a new generalized fractional subequation method to construct exact solutions of space-time fractional coupled differential equations. In order to illustrate the validity and advantages of the algorithm, we

apply it to space-time fractional coupled Konopelchenko-Dubrovsky equations and Nizhnik-Novikov-Veselov equations. As a results, many exact solutions are obtained. The results show that this new generalized fractional subequations method is direct, effective, and can be used for many other fractional coupled differential equations.

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