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81. On a Definition of Singular Integral Operators. I

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Introduction. The theory of singular integral operators of A. P. Calderón and A. Zygmund [1] has been applied to the various problems in partial differential equations, since A. P. Calderón [2] succeeded in proving the general theorem for the uniqueness of solutions of the Cauchy problem by using this theory. S. Mizohata in the notes [7], [8], and [9] proved the many interesting theorems for the uniqueness by modifying the notion of singular integral operators, M. Yamaguti [12] applied these operators to the existence theorem of solutions of the Cauchy problem for hyperbolic differential equations and M. Matsumura [6] applied to the existence and non-existence theorems of local solutions of the general equations.

In the note [4] we introduced singular integral operators of class $C_{\mathfrak{m}}^{m}$ and proved the theorems of [7] and [8] by a unified method, and also in [5] we generalized the theorem of [9] by applying the operators of this class.

In the present note we shall give a definition of singular integral operators which governs operators of class $C_{\mathfrak{M}}^m$, and prove that the main theorems relating to operators of [1] hold for the present operators. In this theory we do not require the homogeneity of the symbol $\sigma(H)(x,\eta)$ in η (Definition 4), but assume the analyticity in η . The technique of almost all the proofs is based on [10] and [12], and the exposition is self-contained. I thank here my colleague K. Ise for helpful discussions.

1. Definitions and lemmas. Let $x=(x_1,\dots,x_n)$ be a point of Euclidean *n*-space R_x^n , $\xi=(\xi_1,\dots,\xi_n)$ be a point of its dual space E_ξ^n and $\alpha=(\alpha_1,\dots,\alpha_n)$ denote a real vector whose elements are nonnegative integers.

We shall use the notations:

$$\alpha! = \alpha_1! \cdots \alpha_n!, \quad |\alpha| = \alpha_1 + \cdots + \alpha_n, \quad x \cdot \xi = x_1 \xi_1 + \cdots + x_n \xi_n,$$

$$D_x = (D_{x_1}, \cdots, D_{x_n}) = (\partial/\partial x_1, \cdots, \partial/\partial x_n), \quad x^{\alpha} = x_1^{\alpha_1} \cdots x_n^{\alpha_n}, \quad D_{\xi} = (\cdots, \text{etc.})$$
The terminology employed is that of L. Schwarz [11].

The Fourier transform $\mathfrak{F}[u](\xi) = \hat{u}(\xi)$ of a function $u \in L_x^2$ is defined by

$$\mathfrak{F}[u](\xi) = \frac{1}{\sqrt{2\pi^n}} \int e^{-\sqrt{-1}x\cdot\xi} u(x) dx.$$